



# Αναπαραστάσεις Αλγεβρών Lie

## Ενότητα 1: Αναπαραστάσεις Αλγεβρών Lie

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- Εισαγωγή.
- Απλές και ημιάπλες Lie άλγεβρες.
- Περιβάλλουσες άλγεβρες.
- Δομή Hopf.
- Αναπαραστάσεις και modules.
- Παραδείγματα εφαρμογών.

- Εισαγωγή των μεταπτυχιακών φοιτητών στην μελέτη και στις τεχνικές αλγεβρών μη προσεταιριστικών όπως είναι οι Lie άλγεβρες.

# Definition of an Algebra

$\mathbb{F}$  = Field of characteristic 0 (ex  $\mathbb{R}$ ,  $\mathbb{C}$ ),

$\alpha, \beta, \dots \in \mathbb{F}$  and  $x, y, \dots \in \mathcal{A}$

## Definition of an Algebra $\mathcal{A}$

$\mathcal{A}$  is a  $\mathbb{F}$ -vector space with an additional distributive binary operation or product

$$\mathcal{A} \times \mathcal{A} \ni (x, y) \xrightarrow{m} m(x, y) = x * y \in \mathcal{A}$$

- $\mathbb{F}$ -vector space

$$\alpha x = x\alpha, (\alpha + \beta)x = \alpha x + \beta x, \alpha(x + y) = \alpha x + \alpha y$$

- distributivity

$$(x + y) * z = x * z + y * z, x * (y + z) = x * y + x * z$$

$$\alpha(x * y) = (\alpha x) * y = x * (\alpha y) = (x * y)\alpha$$

associative algebra  $\equiv (x * y) * z = x * (y * z)$ ,

NON associative algebra  $\equiv (x * y) * z \neq x * (y * z)$

commutative algebra  $\equiv x * y = y * x$ ,

NON commutative algebra  $\equiv x * y \neq y * x$

# Definitions

$\mathbb{F}$  = Field of characteristic 0 (ex  $\mathbb{R}$ ,  $\mathbb{C}$ ),

$\mathfrak{g}$  =  $\mathbb{F}$ -Algebra with a product or **bracket** or **commutator**

$\alpha, \beta, \dots \in \mathbb{F}$  and  $x, y, \dots \in \mathfrak{g}$

$$\mathfrak{g} \times \mathfrak{g} \ni (x, y) \longrightarrow [x, y] \in \mathfrak{g}$$

## Definition :Lie algebra Axioms

- (L-i) **bi-linearity:**  $[\alpha x + \beta y, z] = \alpha [x, z] + \beta [y, z]$   
 $[x, \alpha y + \beta z] = \alpha [x, y] + \beta [x, z]$
- (L-ii) **anti-commutativity:**  $[x, y] = -[y, x] \Leftrightarrow [x, x] = 0$
- (L-iii) **Jacobi identity:**  $[x, [y, z]] + [y, [z, x]] + [z, [x, y]] = 0$   
or **Leibnitz rule:**  $[x, [y, z]] = [[x, y], z] + [y, [x, z]]$

# Examples of Lie algebras (1)

(i)  $\mathfrak{g} = \{\vec{x}, \vec{y}, \dots\}$  real vector space  $\mathbb{R}^3$

$$[\vec{x}, \vec{y}] \equiv \vec{x} \times \vec{y}$$

(ii)  $\mathcal{A}$  associative  $\mathbb{F}$ - algebra  $\rightsquigarrow \mathcal{A}$  a Lie algebra with commutator  
 $[A, B] = AB - BA$

(iii) Angular Momentum in Quantum Mechanics

$$L_1, L_2, L_3 \quad \left\{ \begin{array}{l} \text{operators on} \\ \text{analytic (holomorphic)} \\ \text{functions} \end{array} \right\} f(x, y, z)$$

$$L_1 = y \frac{\partial}{\partial z} - z \frac{\partial}{\partial y}, \quad L_2 = z \frac{\partial}{\partial x} - x \frac{\partial}{\partial z}, \quad L_3 = x \frac{\partial}{\partial y} - y \frac{\partial}{\partial x}$$

$$\mathfrak{g} = \text{span} \{L_1, L_2, L_3\}$$

$$[L_i, L_j] \equiv L_i \circ L_j - L_j \circ L_i$$

$$\rightsquigarrow [L_1, L_2] = -L_3, \quad [L_2, L_3] = -L_1, \quad [L_3, L_1] = -L_2$$



## Examples of Lie algebras (2)

- (iv)  $V = \mathbb{F}$ -vector space,  $\dim V = n < \infty$   
 $b$  bilinear form on  $V$

$$b: V \times V \ni (v, w) \longrightarrow b(v, w) \in \mathbb{F}$$

$$b(\alpha u + \beta v, w) = \alpha b(u, w) + \beta b(v, w)$$

$$b(u, \alpha v + \beta w) = \alpha b(u, v) + \beta b(u, w)$$

$\mathfrak{o}(V, b) = \text{Orthogonal Lie algebra} \equiv$  the set of all  $T \in \text{End } V$

$$b(u, Tv) + b(Tu, v) = 0$$

$$[T_1, T_2] = T_1 \circ T_2 - T_2 \circ T_1$$

$$T_1 \text{ and } T_2 \in \mathfrak{o}(V, b) \rightsquigarrow [T_1, T_2] \in \mathfrak{o}(V, b)$$

# Matrix Formulation for bilinear forms

$$V \ni a \longleftrightarrow \bar{a} = \begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{pmatrix}, \quad \langle \bar{a}, \bar{b} \rangle = \sum_{i=1}^n a_i b_i = (a_1, a_2, \dots, a_n) \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix}$$

$$\text{End}(V) \ni M \longleftrightarrow \mathbb{M} = \begin{pmatrix} M_{11} & M_{12} & \cdots & M_{1n} \\ M_{21} & M_{22} & \cdots & M_{2n} \\ \cdots & \cdots & \cdots & \cdots \\ M_{n1} & M_{n2} & \cdots & M_{nn} \end{pmatrix} \rightsquigarrow \langle \mathbb{M}\bar{a}, \bar{b} \rangle = \langle \bar{a}, \mathbb{M}^{\text{tr}}\bar{b} \rangle$$

bilinear form  $b \longleftrightarrow \mathbb{B}$  matrix  $n \times n \rightsquigarrow b(x, y) = \langle \bar{x}, \mathbb{B}\bar{y} \rangle$

$M \in O(V, b)$

$$b(Mx, My) = b(x, y) \iff \mathbb{M}^{\text{tr}}\mathbb{B}M = \mathbb{B} \iff M^{\text{tr}}bM = b$$

$T \in \mathfrak{o}(V, b)$

$$b(Tx, y) + b(x, Ty) = 0 \iff T^{\text{tr}}\mathbb{B} + \mathbb{B}T = 0_{n \times n} \iff T^{\text{tr}}b + bT = 0$$

- (v) A **Poisson algebra** is a vector space over a field  $\mathbb{F}$  equipped with two bilinear products,  $\cdot$  and  $\{ , \}$ , having the following properties:
- (a) The product  $\cdot$  forms an associative (commutative)  $\mathbb{F}$ -algebra.
  - (b) The product  $\{ , \}$ , called the **Poisson bracket**, forms a Lie algebra, and so it is anti-symmetric, and obeys the Jacobi identity.
  - (c) The Poisson bracket acts as a derivation of the associative product  $\cdot$ , so that for any three elements  $x, y$  and  $z$  in the algebra, one has
$$\{x, y \cdot z\} = \{x, y\} \cdot z + y \cdot \{x, z\}$$

## Example: **Poisson algebra on a Poisson manifold**

$M$  is a manifold,  $C^\infty(M)$  the "smooth" /analytic (complex) functions on the manifold.

$$\{f, g\} = \sum_{ij} \omega_{ij}(x) \frac{\partial f}{\partial x_i} \frac{\partial g}{\partial x_j}$$

$$\omega_{ij}(x) = -\omega_{ji}(x), \quad \sum_m \left( \omega_{km} \frac{\partial \omega_{ij}}{\partial x_m} + \omega_{im} \frac{\partial \omega_{jk}}{\partial x_m} + \omega_{jm} \frac{\partial \omega_{ki}}{\partial x_m} \right) = 0$$

# Structure Constants

$$\mathfrak{g} = \text{span}(e_1, e_2, \dots, e_n) = \mathbb{F}e_1 + \mathbb{F}e_2 + \dots + \mathbb{F}e_n$$

$$[e_i, e_j] = \sum_{k=1}^n c_{ij}^k e_k \equiv c_{ij}^k e_k, \quad c_{ij}^k \longleftrightarrow \text{structure constants}$$

(L-i) **bi-linearity**

(L-ii) **anti-commutativity:**  $c_{ij}^k = -c_{ji}^k$

(L-iii) **Jacobi identity:**  $c_{ij}^m c_{mk}^l + c_{jk}^m c_{mi}^l + c_{ki}^m c_{mj}^l = 0$

summation on **color** indices

# $\mathfrak{gl}(V)$ algebra

$V = \mathbb{F}$ -vector space,  $\dim V = n < \infty$

## general linear algebra $\mathfrak{gl}(V)$

$\mathfrak{gl}(V) \equiv \text{End}(V) =$  endomorphisms on  $V$   $\dim \mathfrak{gl}(V) = n^2$   
 $\mathfrak{gl}(V)$  is a Lie algebra with commutator  $[A, B] = AB - BA$

$\mathfrak{gl}(\mathbb{C}^n) \equiv \mathfrak{gl}(n, \mathbb{C}) \equiv \mathbf{M}_n(\mathbb{C}) \equiv$  complex  $n \times n$  matrices

## Standard basis

Standard basis for  $\mathfrak{gl}(n, \mathbb{C}) =$  matrices  $E_{ij}$  (1 in the  $(i, j)$  position, 0 elsewhere)  $[E_{ij}, E_{kl}] = \delta_{jk}E_{il} - \delta_{il}E_{kj}$

# General Linear Group

$GL(n, \mathbb{F})$  = invertible  $n \times n$  matrices

$M \in GL(n, \mathbb{F}) \iff \det M \neq 0$

$GL(n, \mathbb{C})$  is an analytic manifold of dim  $n^2$  AND a group.

The group multiplication is a continuous application  $G \times G \rightarrow G$

The group inversion is a continuous application  $G \rightarrow G$

## Definition of the Lie algebra from the Lie group

$$\mathfrak{g}(n, \mathbb{C}) = T_{\mathbb{I}}(GL(n, \mathbb{C}))$$

$$\left. \begin{array}{l} X(t) \in GL(n, \mathbb{C}) \\ X(t) \text{ smooth trajectory} \\ X(0) = \mathbb{I} \end{array} \right\} \implies \{X'(0) = x \in \mathfrak{gl}(n, \mathbb{C})\}$$

## Definition of a Lie group from a Lie algebra

$$\{x \in \mathfrak{gl}(n, \mathbb{C})\} \implies \left\{ X(t) = e^{xt} = \sum_{n=0}^{\infty} \frac{t^n}{n!} x^n \in GL(n, \mathbb{F}) \right\}$$

# Jordan decomposition

## Jordan decomposition

- $A \in gl(V) \rightsquigarrow A = A_s + A_n, [A_s, A_n] = A_s A_n - A_n A_s = 0$
- $A_s$  diagonal matrix (or semisimple)
- $A_n$  nilpotent matrix ( $A_n^m = 0$ ), the decomposition is unique

$$x = x_s + x_n$$

$$e^x = \sum_{k=0}^{\infty} \frac{x^k}{k!}$$

$$e^x = e^{(x_s + x_n)} = e^{x_s} e^{x_n}$$

$$x_s \text{ diagonal matrix} = \begin{pmatrix} \lambda_1 & 0 & 0 & \dots & 0 \\ 0 & \lambda_2 & 0 & \dots & 0 \\ & \dots & \dots & \dots & 0 \\ 0 & 0 & 0 & \dots & \lambda_n \end{pmatrix} \Rightarrow$$

$$e^{x_s} \text{ diagonal matrix} = \begin{pmatrix} e^{\lambda_1} & 0 & 0 & \dots & 0 \\ 0 & e^{\lambda_2} & 0 & \dots & 0 \\ & \dots & \dots & \dots & 0 \\ 0 & 0 & 0 & \dots & e^{\lambda_n} \end{pmatrix}$$

$$e^{x_n} = \sum_{k=0}^{m-1} \frac{x_n^k}{k!}$$

# Lie algebra of the (Lie) group of isometries

$V$   $\mathbb{F}$ -vector space,  $b : V \otimes V \rightarrow \mathbb{C}$  bilinear form

$O(V, b)$  = group of isometries on  $V$  i.e.

$$O(V, b) \ni M : V \xrightarrow{\text{lin}} V \rightsquigarrow b(Mu, Mv) = b(u, v)$$

$$\left. \begin{array}{l} M(t) \text{ smooth trajectory } \in O(V, b) \\ M(0) = I \end{array} \right\} \rightsquigarrow$$

$$M'(0) = T \in \mathfrak{o}(V, b) = \text{Lie algebra}$$

$$\implies b(Tu, v) + b(u, Tv) = 0$$

$$\implies T^{\text{tr}} b + b T = 0$$

group of isometries  $O(V, b) \rightarrow$  Lie algebra  $\mathfrak{o}(V, b) = T_{\mathbb{I}}(O(V, b))$

The Lie algebra  $\mathfrak{o}(V, b)$  is the tangent space of the manifold  $O(V, b)$  at the unity  $\mathbb{I}$



# Classical Lie Algebras (1)

$A_\ell$  or  $\mathfrak{sl}(\ell + 1, \mathbb{C})$  or special linear algebra

Def:  $(\ell + 1) \times (\ell + 1)$  complex matrices  $T$  with  $\text{Tr } T = 0$

Dimension =  $\dim(A_\ell) = (\ell + 1)^2 - 1 = \ell(\ell + 2)$

Standard Basis:  $E_{ij}$ ,  $i \neq j$ ,  $i, j = 1, 2, \dots, \ell + 1$ .  $H_i = E_{ii} - E_{i+1, i+1}$

## Classical Lie Algebras (2)

$\mathbb{C}_\ell$  or  $\mathfrak{sp}(2\ell, \mathbb{C})$  or symplectic algebra

Def:  $(2\ell) \times (2\ell)$  complex matrices  $T$  with  $\text{Tr } T = 0$  leaving infinitesimally invariant the bilinear form

$$b \longleftrightarrow \begin{pmatrix} 0_\ell & \mathbb{I}_\ell \\ -\mathbb{I}_\ell & 0_\ell \end{pmatrix}$$

$$\left. \begin{array}{l} U, V \in \mathbb{C}^{2\ell} \\ T \in \mathfrak{sp}(2\ell, \mathbb{C}) \end{array} \right\} \rightsquigarrow b(U, TV) + b(TU, V) = 0$$

$$T = \begin{pmatrix} M & N \\ P & -M^{\text{tr}} \end{pmatrix} \rightsquigarrow \begin{cases} N^{\text{tr}} = N, \\ P^{\text{tr}} = P \end{cases}$$

$$bT + T^{\text{tr}}b = 0 \rightsquigarrow bTb^{-1} = -T^{\text{tr}}$$

# Classical Lie Algebras (3)

$\mathfrak{B}_\ell$  or  $\mathfrak{o}(2\ell + 1, \mathbb{C})$  or (odd) **o**rthogonal algebra

Def:  $(2\ell + 1) \times (2\ell + 1)$  complex matrices  $T$  with  $\text{Tr } T = 0$  leaving infinitesimally invariant the bilinear form

$$b \longleftrightarrow \begin{pmatrix} 1 & \bar{0} & \bar{0} \\ \bar{0}^{\text{tr}} & 0_\ell & \mathbb{I}_\ell \\ \bar{0}^{\text{tr}} & \mathbb{I}_\ell & 0_\ell \end{pmatrix}$$

$$\bar{0} = (0, 0, \dots, 0)$$

$$\left. \begin{array}{l} U, V \in \mathbb{C}^{2\ell} \\ T \in \mathfrak{o}(2\ell + 1, \mathbb{C}) \end{array} \right\} \rightsquigarrow b(U, TV) + b(TU, V) = 0$$

$$T = \begin{pmatrix} 0 & \bar{b} & \bar{c} \\ -\bar{c}^{\text{tr}} & M & N \\ -\bar{b}^{\text{tr}} & P & -M^{\text{tr}} \end{pmatrix} \rightsquigarrow \begin{cases} N^{\text{tr}} = -N, \\ P^{\text{tr}} = -P \end{cases}$$

# Classical Lie Algebras (4)

$\mathfrak{D}_\ell$  or  $\mathfrak{o}(2\ell, \mathbb{C})$  or (even) orthogonal algebra

Def:  $(2\ell) \times (2\ell)$  complex matrices  $T$  with  $\text{Tr } T = 0$  leaving infinitesimally invariant the bilinear form

$$b \longleftrightarrow \begin{pmatrix} 0_\ell & \mathbb{I}_\ell \\ \mathbb{I}_\ell & 0_\ell \end{pmatrix}$$

$$\left. \begin{array}{l} U, V \in \mathbb{C}^{2\ell} \\ T \in \mathfrak{o}(2\ell, \mathbb{C}) \end{array} \right\} \rightsquigarrow b(U, TV) + b(TU, V) = 0$$

$$T = \begin{pmatrix} M & N \\ P & -M^{\text{tr}} \end{pmatrix} \rightsquigarrow \begin{cases} N^{\text{tr}} = -N, \\ P^{\text{tr}} = -P \end{cases}$$

## Definition (Lie subalgebra)

$\mathfrak{h}$  Lie subalgebra  $\mathfrak{g} \Leftrightarrow$

- (i)  $\mathfrak{h}$  vector subspace of  $\mathfrak{g}$
- (ii)  $[\mathfrak{h}, \mathfrak{h}] \subset \mathfrak{h}$

Examples of  $\mathfrak{gl}(n, \mathbb{C})$  subalgebras

**Diagonal matrices**  $\mathfrak{d}(n, \mathbb{C}) =$  matrices with diagonal elements only

$$[\mathfrak{d}(n, \mathbb{C}), \mathfrak{d}(n, \mathbb{C})] = 0_n \subset \mathfrak{d}(n, \mathbb{C})$$

**Upper triangular matrices**  $\mathfrak{t}(n, \mathbb{C})$ ,

**Strictly Upper triangular matrices**  $\mathfrak{n}(n, \mathbb{C})$ ,

$$\mathfrak{n}(n, \mathbb{C}) \subset \mathfrak{t}(n, \mathbb{C})$$

$$[\mathfrak{t}(n, \mathbb{C}), \mathfrak{t}(n, \mathbb{C})] \subset \mathfrak{n}(n, \mathbb{C}), \quad [\mathfrak{n}(n, \mathbb{C}), \mathfrak{n}(n, \mathbb{C})] \subset \mathfrak{n}(n, \mathbb{C})$$

$$[\mathfrak{n}(n, \mathbb{C}), \mathfrak{t}(n, \mathbb{C})] \subset \mathfrak{n}(n, \mathbb{C})$$

ex.  $\mathfrak{sl}(2, \mathbb{C})$  Lie subalgebra of  $\mathfrak{sl}(3, \mathbb{C})$

**Algebra**  $\mathfrak{sl}(2, \mathbb{C}) = \text{span}(h, x, y)$

$$[h, x] = 2x \quad [h, y] = -2y \quad [x, y] = h$$

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ex.  $2 \times 2$  matrices with trace 0

$$h = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \quad x = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \quad y = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$$

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ex. first derivative operators acting on polynomials of order  $n$

$$h = z \frac{\partial}{\partial z} - \frac{n}{2}, \quad x = z^2 \frac{\partial}{\partial z} - nz, \quad y = \frac{\partial}{\partial z}$$

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**Algebra**  $\mathfrak{sl}(3, \mathbb{C}) = \text{span} (h_1, h_2, x_1, y_1, x_2, y_2, x_3, y_3)$

$$\begin{aligned}
 [h_1, h_2] &= 0 \\
 [h_1, x_1] &= 2x_1, & [h_1, y_1] &= -2y_1, & [x_1, y_1] &= h_1, \\
 [h_1, x_2] &= -x_2, & [h_1, y_2] &= y_2, \\
 [h_1, x_3] &= x_3, & [h_1, y_3] &= -y_3, \\
 [h_2, x_2] &= 2x_2, & [h_2, y_2] &= -2y_2, & [x_2, y_2] &= h_2, \\
 [h_2, x_1] &= -x_1, & [h_2, y_1] &= y_1, \\
 [h_2, x_3] &= x_3, & [h_2, y_3] &= -y_3, \\
 [x_1, x_2] &= x_3, & [x_1, x_3] &= 0, & [x_2, x_3] &= 0 \\
 [y_1, y_2] &= -y_3, & [y_1, y_3] &= 0, & [y_2, y_3] &= 0 \\
 [x_1, y_2] &= 0, & [x_1, y_3] &= -y_2, \\
 [x_2, y_1] &= 0, & [x_2, y_3] &= y_1, \\
 [x_3, y_1] &= -x_2, & [x_3, y_2] &= x_1, & [x_3, y_3] &= h_1 + h_2
 \end{aligned}$$

ex.  $3 \times 3$  matrices with trace 0

$$\begin{aligned}
 h_1 &= \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{bmatrix} & x_1 &= \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} & x_2 &= \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} & x_3 &= \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \\
 h_2 &= \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix} & y_1 &= \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} & y_2 &= \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} & y_3 &= \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix}
 \end{aligned}$$

## Definition (Ideal)

**Ideal**  $\mathcal{I}$  is a Lie subalgebra such that  $[\mathcal{I}, \mathfrak{g}] \subset \mathcal{I}$

**Center**  $\mathcal{Z}(\mathfrak{g}) = \{z \in \mathfrak{g} : [z, \mathfrak{g}] = 0\}$

**Prop:** The center is an ideal.

**Prop:** The **derived algebra**  $\equiv \mathcal{D}\mathfrak{g} = [\mathfrak{g}, \mathfrak{g}]$  is an ideal.

**Prop:** If  $\mathcal{I}, \mathcal{J}$  are ideals  $\Rightarrow \mathcal{I} + \mathcal{J}, [\mathcal{I}, \mathcal{J}]$  and  $\mathcal{I} \cap \mathcal{J}$  are ideals.

## Theorem

$\mathcal{I}$  ideal of  $\mathfrak{g} \rightsquigarrow \mathfrak{g}/\mathcal{I} \equiv \{\bar{x} = x + \mathcal{I} : x \in \mathfrak{g}\}$  is a Lie algebra

$$[\bar{x}, \bar{y}] \equiv \overline{[x, y]} = [x, y] + \mathcal{I}$$



**Def:**  $\mathfrak{g}$  is **simple**  $\Leftrightarrow \mathfrak{g}$  has **only** trivial ideals and  $[\mathfrak{g}, \mathfrak{g}] \neq \{0\}$   
(trivial ideals of  $\mathfrak{g}$  are the ideals  $\{0\}$  and  $\mathfrak{g}$ )

**Def:**  $\mathfrak{g}$  is **abelian**  $\Leftrightarrow [\mathfrak{g}, \mathfrak{g}] = \{0\}$

**Prop:**  $\mathfrak{g}/[\mathfrak{g}, \mathfrak{g}]$  is abelian

**Prop:**  $\mathfrak{g}$  is **simple Lie algebra**  $\Rightarrow \mathcal{Z}(\mathfrak{g}) = 0$  and  $\mathfrak{g} = [\mathfrak{g}, \mathfrak{g}]$ .

**Prop:** The Classical Lie Algebras  $A_\ell, B_\ell, C_\ell, D_\ell$  are simple Lie Algebras

# Direct Sum of Lie Algebras

$\mathfrak{g}_1, \mathfrak{g}_2$  Lie algebras

direct sum  $\mathfrak{g}_1 \oplus \mathfrak{g}_2 = \mathfrak{g}_1 \times \mathfrak{g}_2$  with the following structure:

$$\alpha(x_1, x_2) + \beta(y_1, y_2) \equiv (\alpha x_1 + \beta y_1, \alpha x_2 + \beta y_2)$$

$\rightsquigarrow \mathfrak{g}_1 \oplus \mathfrak{g}_2$  vector space

commutator definition:  $[(x_1, x_2), (y_1, y_2)] \equiv ([x_1, y_1], [x_2, y_2])$

**Prop:**  $\mathfrak{g}_1 \oplus \mathfrak{g}_2$  is a Lie algebra

$$\left. \begin{array}{l} (\mathfrak{g}_1, 0) \underset{\text{iso}}{\simeq} \mathfrak{g}_1 \\ (0, \mathfrak{g}_2) \underset{\text{iso}}{\simeq} \mathfrak{g}_2 \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{l} (\mathfrak{g}_1, 0) \cap (0, \mathfrak{g}_2) = \{(0, 0)\} \iff \mathfrak{g}_1 \cap \mathfrak{g}_2 = 0 \\ [(\mathfrak{g}_1, 0), (0, \mathfrak{g}_2)] = \{(0, 0)\} \iff [\mathfrak{g}_1, \mathfrak{g}_2] = 0 \end{array} \right.$$

**Prop:**  $\mathfrak{g}_1$  and  $\mathfrak{g}_2$  are ideals of  $\mathfrak{g}_1 \oplus \mathfrak{g}_2$

$$\text{Prop: } \left\{ \begin{array}{l} \mathfrak{a}, \mathfrak{b} \text{ ideals of } \mathfrak{g} \\ \mathfrak{a} \cap \mathfrak{b} = \{0\} \\ \mathfrak{a} + \mathfrak{b} = \mathfrak{g} \end{array} \right\} \rightsquigarrow \left\{ \mathfrak{a} \oplus \mathfrak{b} \underset{\text{iso}}{\longleftrightarrow} \mathfrak{a} + \mathfrak{b} \right\} \rightsquigarrow \left\{ \mathfrak{a} \oplus \mathfrak{b} = \mathfrak{g} \right\}$$

# Lie homomorphisms

**homomorphism:**

$$\mathfrak{g} \xrightarrow{\phi} \mathfrak{g}' \quad \left\{ \begin{array}{l} \text{(i)} \quad \phi \text{ linear} \\ \text{(ii)} \quad \phi([x, y]) = [\phi(x), \phi(y)] \end{array} \right.$$

**monomorphism:**  $\text{Ker } \phi = \{0\}$ ,

**epimorphism:**  $\text{Im } \phi = \mathfrak{g}'$

**isomorphism:** mono+ epi,

**automorphism:** iso+  $\{\mathfrak{g} = \mathfrak{g}'\}$

**Prop:**  $\text{Ker } \phi$  is an ideal of  $\mathfrak{g}$

**Prop:**  $\text{Im } \phi = \phi(\mathfrak{g})$  is Lie subalgebra of  $\mathfrak{g}'$

## Theorem

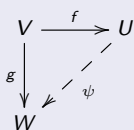
$$\left\{ \begin{array}{l} \mathfrak{I} \text{ ideal of } \mathfrak{g} \\ \text{canonical map } \mathfrak{g} \xrightarrow{\pi} \mathfrak{g}/\mathfrak{I} \\ \pi(x) = \bar{x} = x + \mathfrak{I} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{l} \text{canonical map is a} \\ \text{Lie epimorphism} \end{array} \right\}$$

# Linear homomorphism theorem

## Theorem

$V, U, W$  linear spaces

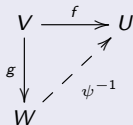
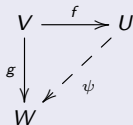
$f : V \rightarrow U$  and  $g : V \rightarrow W$  linear maps



$$\left\{ \begin{array}{l} f \text{ epi} \\ \text{Ker } f \subset \text{Ker } g \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{l} \exists! \psi : \\ g = \psi \circ f \end{array} \right\}$$

$$\text{Ker } \psi = f(\text{Ker } g)$$

## Corollary



$$\left\{ f \text{ epi}, g \text{ epi}, \text{Ker } f = \text{Ker } g \right\} \rightsquigarrow \left\{ \exists! \psi \text{ iso} : g = \psi \circ f, U \underset{\text{iso}}{\simeq} W \right\}$$

# Lie homomorphism theorem

## Theorem

$\mathfrak{g}, \mathfrak{h}, \mathfrak{l}$  Lie spaces,  $\phi : \mathfrak{g} \xrightarrow{\text{epi}} \mathfrak{h}$  and  $\rho : \mathfrak{g} \rightarrow \mathfrak{l}$  Lie homomorphisms

$$\begin{array}{ccc} \mathfrak{g} & \xrightarrow{\phi} & \mathfrak{h} \\ \rho \downarrow & \swarrow \psi & \\ \mathfrak{l} & & \end{array} \quad \left\{ \begin{array}{l} \phi \text{ Lie-epi,} \\ \text{Ker } \phi \subset \text{Ker } \rho \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{l} \exists! \psi : \text{Lie-homo} \\ \rho = \psi \circ \phi \end{array} \right\}$$

## Corollary

$$\begin{array}{ccc} \mathfrak{g} & \xrightarrow{\phi} & \mathfrak{h} \\ \rho \downarrow & \swarrow \psi & \\ \mathfrak{l} & & \end{array} \quad \begin{array}{ccc} \mathfrak{g} & \xrightarrow{\phi} & \mathfrak{h} \\ \rho \downarrow & \swarrow \psi^{-1} & \\ \mathfrak{l} & & \end{array}$$

$$\left\{ \phi \text{ Lie-epi, } \rho \text{ Lie-epi, } \text{Ker } \phi = \text{Ker } \rho \right\} \rightsquigarrow \left\{ \exists! \psi : \text{Lie-iso } \rho = \psi \circ \phi, \mathfrak{h} \underset{\text{iso}}{\simeq} \mathfrak{l} \right\}$$

# First isomorphism theorem

## Theorem (First isomorphism theorem)

$\phi : \mathfrak{g} \longrightarrow \mathfrak{g}'$  Lie-homomorphism,

$$\begin{array}{ccc} \mathfrak{g} & \xrightarrow{\pi} & \mathfrak{g}/\text{Ker } \phi \\ \phi \downarrow & \swarrow \text{---} & \\ \phi(\mathfrak{g}) & & \end{array} \implies \exists! \phi' : \mathfrak{g}/\text{Ker } \phi \longrightarrow \phi(\mathfrak{g}) \subset \mathfrak{g}' \text{ Lie-iso}$$

$$\phi(\mathfrak{g}) \underset{\text{iso}}{\simeq} \mathfrak{g}/\text{Ker } \phi$$

# Noether Theorems

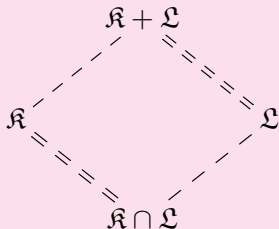
## Theorem

$$\left. \begin{array}{l} \mathfrak{K}, \mathfrak{L} \\ \text{ideals of } \mathfrak{g} \\ \mathfrak{K} \subset \mathfrak{L} \end{array} \right\} \rightsquigarrow \left\{ \begin{array}{l} (i) \quad \mathfrak{L}/\mathfrak{K} \text{ ideal of } \mathfrak{g}/\mathfrak{K} \\ (ii) \quad (\mathfrak{g}/\mathfrak{K}) / (\mathfrak{L}/\mathfrak{K}) \underset{\text{iso}}{\simeq} (\mathfrak{g}/\mathfrak{L}) \end{array} \right.$$

## Theorem ( Noether Theorem (2nd isomorphism theor.) )

$$\left\{ \begin{array}{l} \mathfrak{K}, \mathfrak{L} \\ \text{ideals of } \mathfrak{g} \end{array} \right\} \rightsquigarrow \left\{ (\mathfrak{K} + \mathfrak{L})/\mathfrak{L} \underset{\text{iso}}{\simeq} \mathfrak{K}/(\mathfrak{K} \cap \mathfrak{L}) \right\}$$

Parallelogram Law:



$\mathcal{A}$  an  $\mathbb{F}$ -algebra (not necessary associative) with product  $\diamond$

$$\mathcal{A} \times \mathcal{A} \ni (a, b) \longrightarrow a \diamond b \in \mathcal{A}$$

$\diamond$  bilinear mapping,  $\partial$  is a **derivation** of  $\mathcal{A}$  if  $\partial$  is a linear map  $\mathcal{A} \xrightarrow{\partial} \mathcal{A}$  satisfying the **Leibnitz** property:

$$\partial(A \diamond B) = A \diamond (\partial(B)) + (\partial(A)) \diamond B$$

$\mathfrak{Der}(\mathcal{A}) =$  all derivations on  $\mathcal{A}$

**Prop:**  $\mathfrak{Der}(\mathcal{A})$  is a Lie Algebra  $\subset \mathfrak{gl}(\mathcal{A})$  with commutator  
 $[\partial, \partial'](A) \equiv \partial(\partial'(A)) - \partial'(\partial(A))$



# Derivations on a Lie algebra

$\mathfrak{g}$  a  $\mathbb{F}$ - Lie algebra,  $\partial$  is a Lie derivation of  $\mathfrak{g}$  if  $\partial$  is a linear map:

$$\mathfrak{g} \ni x \xrightarrow{\partial} \partial(x) \in \mathfrak{g}$$

satisfying the Leibnitz property :  $\partial([x, y]) = [\partial(x), y] + [x, \partial(y)]$

$\mathfrak{Der}(\mathfrak{g}) =$  all derivations on  $\mathfrak{g}$

**Prop:**  $\mathfrak{Der}(\mathfrak{g})$  is a Lie Algebra  $\subset \mathfrak{gl}(\mathfrak{g})$  with commutator  
 $[\partial, \partial'](x) \equiv \partial(\partial'(x)) - \partial'(\partial(x))$

**Prop:**  $\delta \in \mathfrak{Der}(\mathfrak{g}) \rightsquigarrow \delta^n([x, y]) = \sum_{k=0}^n \binom{n}{k} [\delta^k(x), \delta^{n-k}(y)]$

**Prop:**  $\delta \in \mathfrak{Der}(\mathfrak{g}) \rightsquigarrow e^\delta([x, y]) = [e^\delta(x), e^\delta(y)] \iff e^\delta \in \text{Aut}(\mathfrak{g})$

## Proposition

$\phi(t)$  smooth monoparametric family in  $\text{Aut}(\mathfrak{g})$  and  $\phi(0) = \text{Id} \rightsquigarrow \phi'(0) \in \mathfrak{Der}(\mathfrak{g})$

# Adjoint Representation

## Definition (Adjoint Representation)

Let  $x \in \mathfrak{g}$  and  $\text{ad}_x : \mathfrak{g} \rightarrow \mathfrak{g} : \text{ad}_x(y) = [x, y]$

**Prop:**  $\text{ad}_{[x,y]} = [\text{ad}_x, \text{ad}_y]$

**Prop:**  $\text{ad}_{\mathfrak{g}} \equiv \bigcup_{x \in \mathfrak{g}} \{\text{ad}_x\}$  Lie-subalgebra of  $\mathfrak{Der}(\mathfrak{g})$

Definition: **Inner Derivations** =  $\text{ad}_{\mathfrak{g}}$

Definition **Outer Derivations** =  $\mathfrak{Der}(\mathfrak{g}) \setminus \text{ad}_{\mathfrak{g}}$

**Prop:**  $\left\{ \begin{array}{l} x \in \mathfrak{g} \\ \delta \in \mathfrak{Der}(\mathfrak{g}) \end{array} \right\} \rightsquigarrow \left\{ [\text{ad}_x, \delta] = -\text{ad}_{\delta(x)} \right\} \rightsquigarrow \left\{ \begin{array}{l} \text{ad}_{\mathfrak{g}} \\ \text{ideal of} \\ \mathfrak{Der}(\mathfrak{g}) \end{array} \right\}$

**Prop:**

$\tau \in \text{Aut}(\mathfrak{g}) \iff \tau([x, y]) = [\tau(x), \tau(y)] \rightsquigarrow \text{ad}_{\tau(x)} = \tau \circ \text{ad}_x \circ \tau^{-1}$

# Matrix Form of the adjoint representation

$$\mathfrak{g} = \text{span}(e_1, e_2, \dots, e_n) = \mathbb{C}e_1 + \mathbb{C}e_2 + \dots + \mathbb{C}e_n$$

$$[e_i, e_j] = \sum_{k=1}^n c_{ij}^k e_k, \quad c_{ij}^k \longleftrightarrow \text{structure constants}$$

**Antisymmetry:**  $c_{ij}^k = -c_{ji}^k$

**Jacobi identity**  $c_{ij}^m c_{mk}^\ell + c_{jk}^m c_{mi}^\ell + c_{ki}^m c_{mj}^\ell = 0$

$$e^\ell = e_\ell^* \in \mathfrak{g}^* \rightsquigarrow e_\ell^* \cdot e_p = e^\ell \cdot e_p = \delta_p^\ell$$

$$\mathbb{P}_i \in \mathfrak{gl}(\mathfrak{g}) : e^k \cdot \mathbb{P}_i e_j = (\mathbb{P}_i)_j^k = c_{ij}^k \rightsquigarrow$$

$$[\mathbb{P}_i, \mathbb{P}_j] = \sum_{k=1}^n c_{ij}^k \mathbb{P}_k \rightsquigarrow$$

$$\mathbb{P}_i = \text{ad}_{e_i}$$

# Representations, Modules

$V$   $\mathbb{F}$ -vector space,  $u, v, \dots \in V$ ,  $\alpha, \beta, \dots \in \mathbb{F}$

## Definition

Representation  $(\rho, V)$

$$\mathfrak{g} \ni x \xrightarrow{\rho} \rho(x) \in \mathfrak{gl}(V)$$

$$V \ni v \xrightarrow{\rho(x)} \rho(x)v \in V$$

$\rho(x)$  Lie homomorphism

$$\rho(\alpha x + \beta y) = \alpha \rho(x) + \beta \rho(y)$$

$$\rho([x, y]) = [\rho(x), \rho(y)] =$$

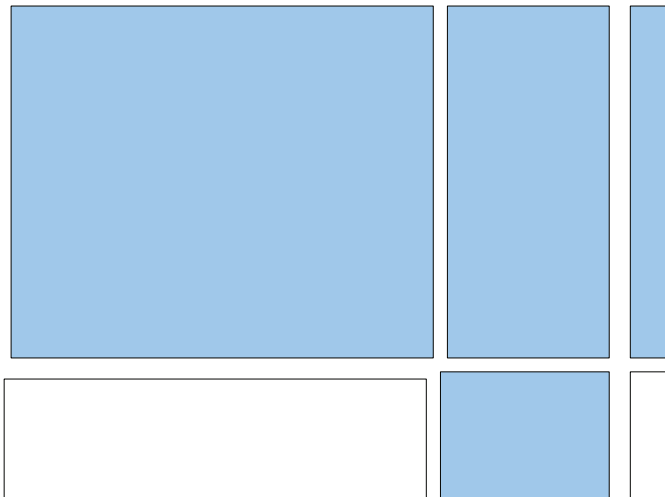
$$= \rho(x) \circ \rho(y) - \rho(y) \circ \rho(x)$$

$V = \mathbb{C}^n \rightsquigarrow \rho(x) \in M_n(\mathbb{C}) = \mathfrak{gl}(V) = \mathfrak{gl}(\mathbb{C}, n)$

$W \subset V$  invariant (stable) subspace

$$\iff \rho(\mathfrak{g})W \subset W$$

$$\iff (\rho, W) \text{ is submodule} \iff (\rho, W) \prec (\rho, V)$$



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# Theorem (1)

## Theorem

$W$  invariant subspace of  $V \iff (\rho, W) \prec (\rho, V)$

$(\rho, V) \rightsquigarrow \exists! \boxed{\text{induced representation}} (\bar{\rho}, V/W)$

$$\rho(\mathfrak{g})W \subset W \implies \exists! \bar{\rho}(x) : V/W \longrightarrow V/W$$

$$\implies \begin{array}{ccc} V & \xrightarrow{\pi} & V/W \\ \rho(x) \downarrow & \swarrow \text{dotted} & \downarrow \bar{\rho}(x) \\ V & \xrightarrow{\pi} & V/W \end{array} \iff \bar{\rho}(x) \circ \pi = \pi \circ \rho(x)$$

$\text{Ker } \rho = C_\rho(\mathfrak{g}) = \{x \in \mathfrak{g} : \rho(x)V = \{0\}\}$  is an ideal

$\text{Ker } \text{ad} = C_{\text{ad}}(\mathfrak{g}) = \mathcal{Z}(\mathfrak{g}) = \text{center}$  of  $\mathfrak{g}$

# Reducible and Irreducible representation

$(\rho, V)$  irreducible/simple representation (irrep)

$\iff \nexists$  (non trivial) invariant subspaces

$\iff \rho(\mathfrak{g})W \subset W \Rightarrow W = \{0\}$  or  $V$

$\iff (\rho, W) \prec (\rho, V) \Rightarrow W = \{0\}$  or  $V$

---

$(\rho, V)$  reducible/semisimple representation

$\iff V = V_1 \oplus V_2$ ,  $(\rho, V_1)$  and  $(\rho, V_2)$  submodules

$V = V_1 \oplus V_2 \rightsquigarrow \rho(\mathfrak{g})V_1 \subset V_1, \quad \rho(\mathfrak{g})V_2 \subset V_2$

---

trivial representation  $\iff V = \mathbb{F} \iff \dim V = 1$

# Induced Representation

$$(\rho, W) \prec (\rho, V)$$

$$\rightsquigarrow \begin{array}{ccc} V & \xrightarrow{\pi} & V/W \\ \rho(x) \downarrow & \searrow & \downarrow \bar{\rho}(x) \\ V & \xrightarrow{\pi} & V/W \end{array} \iff \bar{\rho}(x) \circ \pi = \pi \circ \rho(x)$$

$\bar{\rho}(x)$  is the induced representation



# Jordan Hölder decomposition (1)

$(\rho, W) \prec (\rho, V)$  and  $(\bar{\rho}, V/W)$  not irrep nor trivial

$\rightsquigarrow \exists (\bar{\rho}, \bar{U}) \prec (\bar{\rho}, V/W) \rightsquigarrow W \subset U = \pi^{-1}(\bar{U}) \subset V$

$$\rightsquigarrow \begin{array}{ccc} V & \xrightarrow{\pi} & V/W \\ \rho(x) \downarrow & \searrow & \downarrow \bar{\rho}(x) \\ V & \xrightarrow{\pi} & V/W \end{array} \iff \bar{\rho}(x) \circ \pi = \pi \circ \rho(x)$$

$(\pi \circ \rho(x))(U) = (\bar{\rho}(x) \circ \pi)(U) = \bar{\rho}(x)(\bar{U}) \subset \bar{U} = \pi(U) \rightsquigarrow \rho(x)(U) \subset U$

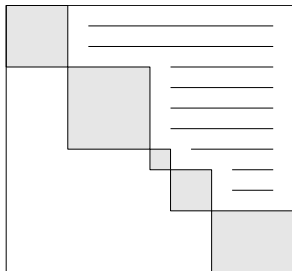
$\rightsquigarrow (\rho, W) \prec (\rho, U) \prec (\rho, V)$

## Theorem (Jordan Hölder decomposition)

$(\rho, V)$  representation

$$V = V_0 \supset V_1 \supset V_2 \supset \cdots \supset V_m = \{0\}, (\rho, V_i) \succ (\rho, V_{i+1}) \\ \left( \bar{\rho}_{V_i/V_{i+1}}, V_i/V_{i+1} \right) \text{ irrep or trivial}$$

## Jordan Hölder decomposition (2)



# Direct sum of representations

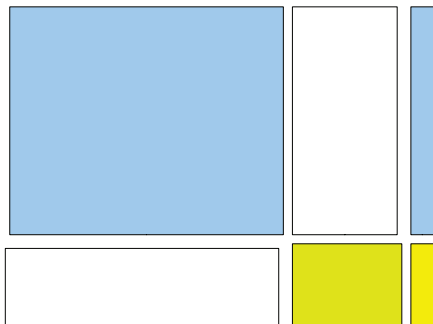
$(\rho_1, V_1), (\rho_2, V_2)$  representations of  $\mathfrak{g}$

**Def:** **Direct sum of representations**  $(\rho_1 \oplus \rho_2, V_1 \oplus V_2)$

$$(\rho_1 \oplus \rho_2)(x) : V_1 \oplus V_2 \longrightarrow V_1 \oplus V_2$$

$$V_1 \oplus V_2 \ni (v_1, v_2) \longrightarrow (\rho_1(x)v_1, \rho_2(x)v_2) \in V_1 \oplus V_2$$

$$V_1 \oplus V_2 \ni v_1 + v_2 \longrightarrow \rho_1(x)v_1 + \rho_2(x)v_2 \in V_1 \oplus V_2$$



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# Theorem (Jordan- Hölder)

## Theorem

*Jordan- Hölder  $\rightsquigarrow$  Any representation of a simple Lie algebra is a direct sum of simple representations or trivial representations*

⇒ **The important is to study the simple representations!**

Theorem (Jordan Hölder decomposition)

$(\rho, V)$  representation

$$V = V_0 \supset V_1 \supset V_2 \supset \cdots \supset V_m = \{0\}, (\rho, V_i) \succ (\rho, V_{i+1}) \\ \left( \bar{\rho}_{V_i/V_{i+1}}, V_i/V_{i+1} \right) \text{ irrep or trivial}$$

$$V = V_{m-1} \oplus V_{m-2}/V_{m-1} \oplus \cdots \oplus V_1/V_2 \oplus V/V_1$$

$$\rho = \rho_{m-1} \oplus \rho_{m-2} \oplus \cdots \oplus \rho_1 \oplus \rho_0$$

$$\rho_{m-1} = \bar{\rho}_{V_{m-1}} \text{ trivial}, \rho_i = \bar{\rho}_{V_i/V_{i+1}} \text{ simple}$$

# Tensor Product of linear spaces- Universal Definition

$\mathbb{F}$  field,  $\mathbb{F}$ - vector spaces  $A, B$

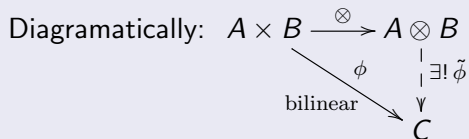
## Definition

Tensor Product  $\equiv \boxed{A \otimes_{\mathbb{F}} B}$  is a  $\mathbb{F}$ -vector space AND a canonical bilinear homomorphism

$$\otimes : A \times B \rightarrow A \otimes B,$$

with the universal property.

Every  $\mathbb{F}$ -bilinear form  $\phi : A \times B \rightarrow C$ ,  
lifts to a unique homomorphism  $\tilde{\phi} : A \otimes B \rightarrow C$ ,  
such that  $\phi(a, b) = \tilde{\phi}(a \otimes b)$  for all  $a \in A, b \in B$ .



## Definition

Tensor product  $A \otimes_{\mathbb{F}} B$  can be constructed by taking the free  $\mathbb{F}$ -vector space generated by all formal symbols

$$a \otimes b, \quad a \in A, b \in B,$$

and quotienting by the bilinear relations:

$$\begin{aligned}(a_1 + a_2) \otimes b &= a_1 \otimes b + a_2 \otimes b, \\ a \otimes (b_1 + b_2) &= a \otimes b_1 + a \otimes b_2, \\ r(a \otimes b) &= (ra) \otimes b = a \otimes (rb)\end{aligned}$$

$$a_1, a_2 \in A, b \in B, a \in A, b_1, b_2 \in B, r \in \mathbb{F}$$

# Examples (1)

**Examples:**  $U$  and  $V$  linear spaces

$$u = \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{bmatrix} \in U, \quad v = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_m \end{bmatrix} \in V \quad \rightsquigarrow \quad u \otimes v = \begin{bmatrix} u_1 v_1 \\ u_1 v_2 \\ \vdots \\ u_1 v_m \\ \hline u_2 v_1 \\ u_2 v_2 \\ \vdots \\ u_2 v_m \\ \hline \vdots \\ \hline u_n v_1 \\ u_n v_2 \\ \vdots \\ u_n v_m \end{bmatrix} \in U \otimes V$$



## Examples (2)

$$U \in \text{End}(U), \quad V \in \text{End}(V)$$

$$U = \begin{bmatrix} u_{11} & u_{12} & \cdots & u_{1n} \\ u_{21} & u_{22} & \cdots & u_{2n} \\ \vdots & \vdots & \vdots & \vdots \\ u_{n1} & u_{n2} & \cdots & u_{nn} \end{bmatrix}$$

$$V = \begin{bmatrix} v_{11} & v_{12} & \cdots & v_{1m} \\ v_{21} & v_{22} & \cdots & v_{2m} \\ \vdots & \vdots & \vdots & \vdots \\ v_{m1} & v_{m2} & \cdots & v_{mm} \end{bmatrix}$$

$$U \otimes V = \begin{bmatrix} u_{11}V & u_{12}V & \cdots & u_{1n}V \\ u_{21}V & u_{22}V & \cdots & u_{2n}V \\ \vdots & \vdots & \vdots & \vdots \\ u_{n1}V & u_{n2}V & \cdots & u_{nn}V \end{bmatrix}$$

$$U \otimes V \in \text{End}(U \otimes V)$$

$$(U \otimes V)(u \otimes v) \equiv Uu \otimes Vv$$

$$(U_1 \otimes V_1)(U_2 \otimes V_2) \equiv U_1U_2 \otimes V_1V_2$$

# Tensor product of representations

$(\rho_1, V_1)$ ,  $(\rho_2, V_2)$  representations of the Lie algebra  $\mathfrak{g}$ .

Tensor product representation  $\left( \rho_1 \overset{\text{L}}{\otimes} \rho_2, V_1 \otimes V_2 \right)$

$$\begin{aligned} \left( \rho_1 \overset{\text{L}}{\otimes} \rho_2 \right) (x) &: V_1 \otimes V_2 \longrightarrow V_1 \otimes V_2 \\ v_1 \otimes v_2 &\longrightarrow \left( \rho_1 \overset{\text{L}}{\otimes} \rho_2 \right) (x) (v_1 \otimes v_2) \end{aligned}$$

$$\left( \rho_1 \overset{\text{L}}{\otimes} \rho_2 \right) (x) (v_1 \otimes v_2) = \rho_1(x)v_1 \otimes v_2 + v_1 \otimes \rho_2(x)v_2$$

$$\left( \rho_1 \overset{\text{L}}{\otimes} \rho_2 \right) (x) = \rho_1(x) \otimes \text{Id}_2 + \text{Id}_1 \otimes \rho_2(x)$$

# Dual representation

$V^*$  dual space of  $V$ ,  $V^* \ni u^* : V \ni v \longrightarrow u^*.v \in \mathbb{C}$

$(\rho, V)$  representation of  $\mathfrak{g} \rightsquigarrow \exists!$  **dual representation**  $(\rho^D, V^*)$

$$\rho^D(x) : V^* \ni u^* \longrightarrow \rho^D(x)u^* \in V^*$$

$$\rho^D(x) = -\rho^*(x) \rightsquigarrow \rho^D(x)u^*.v = -u^*.\rho(x)v$$

$$\begin{aligned}\rho^D(\alpha x + \beta y) &= \alpha \rho^D(x) + \beta \rho^D(y) \\ \rho^D([x, y]) &= [\rho^D(x), \rho^D(y)]\end{aligned}$$

# $\mathfrak{sl}(2, \mathbb{C})$ representations (1)

$$\mathfrak{sl}(2, \mathbb{C}) = \text{span}(h, x, y)$$

$$[h, x] = 2x \quad [h, y] = -2y \quad [x, y] = h$$

$(\rho, V)$  irrep of  $\mathfrak{sl}(2, \mathbb{C})$

Jordan decomposition  $\rightsquigarrow V = \bigoplus_{\lambda} V_{\lambda}$ ,  $\lambda$  eigenvalue of  $\rho(h)$ ,

$$V_{\lambda} = \text{Ker}(\rho(h) - \lambda \mathbb{I})^{n_{\lambda}}, v \in V_{\lambda} \rightsquigarrow \rho(h)v = \lambda v, V_{\lambda} \cap V_{\mu} = \{0\}$$

If  $v$  eigenvector of  $\rho(h)$  with eigenvalue  $\lambda \rightsquigarrow v \in V_{\lambda}$

$\rightsquigarrow \rho(x)v$  eigenvector with eigenvalue  $\lambda + 2 \rightsquigarrow \rho(x)v \in V_{\lambda+2}$

$\rightsquigarrow \rho(y)v$  eigenvector with eigenvalue  $\lambda - 2 \rightsquigarrow \rho(y)v \in V_{\lambda-2}$

$$\rho(h)v = \lambda v \rightsquigarrow \rho(h)\rho(x)v = (\lambda + 2)\rho(x)v \text{ and } \rho(h)\rho(y)v = (\lambda - 2)\rho(y)v$$

$\exists v_0 \in V$ ,  $v$  eigenvector of  $\rho(h)$  such that  $\rho(x)v_0 = 0$

If  $(\rho, V)$  is a finite dimensional representation of  $\mathfrak{sl}(2, \mathbb{C})$  then for every  $z \in \mathfrak{sl}(2, \mathbb{C}) \rightsquigarrow \text{Tr}\rho(z) = 0$

## $\mathfrak{sl}(2, \mathbb{C})$ representations (2)

Let  $\rho(h)v_0 = \mu v_0$  and  $\rho(x)v_0 = 0 \rightsquigarrow \exists n \in \mathbb{N} : \rho(y)^{n+1}v_0 = 0$

$$\begin{aligned}\rho(x)v_0 &= 0, & v_k &= \frac{1}{k!} (\rho(y))^k v_0 \\ \rho(h)v_k &= (\mu - 2k)v_k \\ \rho(y)v_k &= (k+1)v_{k+1} \\ \rho(x)v_k &= (\mu - k + 1)v_{k-1}\end{aligned}$$

$W = \text{span}(v_0, v_1, \dots, v_n)$  and  $\rho(z)W \subset W \forall z \in \mathfrak{sl}(2, \mathbb{C})$

$(\rho, W)$  submodule of  $(\rho, V)$

$$\rho(h) = \begin{bmatrix} \mu & 0 & 0 & \dots & 0 \\ 0 & \mu - 2 & 0 & \dots & 0 \\ 0 & 0 & \mu - 4 & \dots & 0 \\ \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & \dots & \mu - 2n \end{bmatrix}$$

$$\text{Tr } \rho(h) = 0 \rightsquigarrow \mu = n$$

# Theorem (2.1)

## Theorem

$(\rho, V)$  irrep of  $\mathfrak{sl}(2, \mathbb{C}) \Leftrightarrow V = \text{span}(v_0, v_1, \dots, v_n)$

$$\rho(x)v_0 = 0, \quad v_k = \frac{1}{k!} (\rho(y))^k v_0$$

$$\rho(h)v_k = (n - 2k)v_k$$

$$\rho(y)v_k = (k + 1)v_{k+1}$$

$$\rho(x)v_k = (n - k + 1)v_{k-1}$$

$\rho(x)v_k = \mu_k v_k \rightsquigarrow \mu_k = n - 2k$ ,  $\mu_k$  are the weights of the representation.

$$\mu_k = n, n - 2, n - 4, \dots, -n + 4, -n + 2, -n$$

$n$  is the **highest weight** of the irrep

# Theorem (2.2)

$$\rho(x)v_0 = 0, \quad v_k = \frac{1}{k!} (\rho(y))^k v_0$$

$$\rho(h)v_k = (n - 2k)v_k, \quad \rho(y)v_k = (k + 1)v_{k+1}, \quad \rho(x)v_k = (n - k + 1)v_{k-1}$$

$$\rho(h) = \begin{pmatrix} n & 0 & 0 & \cdots & 0 & 0 \\ 0 & n-2 & 0 & \cdots & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & -n+2 & 0 \\ 0 & 0 & 0 & \cdots & 0 & -n \end{pmatrix}$$

$$\rho(x) = \begin{pmatrix} 0 & n & 0 & \cdots & 0 & 0 \\ 0 & 0 & n-1 & \cdots & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & 0 & 1 \\ 0 & 0 & 0 & \cdots & 0 & 0 \end{pmatrix}$$

$$\rho(y) = \begin{pmatrix} 0 & 0 & 0 & \cdots & 0 & 0 \\ 1 & 0 & 0 & \cdots & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & 0 & \\ 0 & 0 & 0 & \cdots & n & 0 \end{pmatrix}$$

# Theorem (2.3)

$$\dim V = n + 1$$

Eigenvalues

$$-n, -n + 2, \dots, n - 2, n$$

irreducible representation  $(\rho, V)$

$$\rho(x)v_0 = 0, \quad v_k = \frac{1}{k!} (\rho(y))^k v_0$$

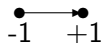
$$\rho(y)^{n+1}v_0 = 0$$

$$\rho(h)v_k = (n - 2k)v_k$$

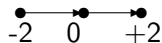
$$\rho(y)v_k = (k + 1)v_{k+1}$$

$$\rho(x)v_k = (n - k + 1)v_{k-1}$$

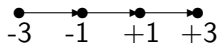
$$\alpha = 2$$



$$\alpha = 2$$



$$\alpha = 2$$



$$\mathfrak{g} = [\mathfrak{g}, \mathfrak{g}]$$



## Weyl Theorem

Any representation  $V = \bigoplus_n k_n V_n$ ,  $V_n$  irrep

## Theorem

*For any finite dimensional representation  $(\rho, V)$  the decomposition in direct sum of irreps is unique. The eigenvalues of  $\rho(h)$  are integers.*

# Weyl Theorem $\mathfrak{sl}(2)$

## Casimir definition

$(\rho, V)$  a representation of  $\mathfrak{g} = \mathfrak{sl}(2, \mathbb{C})$ . The Casimir (operator)  $K_\rho$  corresponding to this representation is an element in  $\text{End } V$  such that

$$K_\rho = \rho^2(h) + 2(\rho(x)\rho(y) + \rho(y)\rho(x)) \rightsquigarrow [K_\rho, \rho(\mathfrak{g})] = \{0\}$$

$V = \bigoplus_{\lambda} V_\lambda$ ,  $\lambda$  are eigenvalues of  $K_\rho \rightsquigarrow (\rho, V_\lambda)$  is submodule of  $(\rho, V)$ .

Any representation (module) of  $\mathfrak{g} = \mathfrak{sl}(2, \mathbb{C})$  contains a submodule  $(\rho, V_n)$ , which is an irreducible representation.

The eigenvalues  $\lambda$  of the Casimir (operator) are given by the formula  $\lambda = n(n+2)$ , where  $n = 0, 1, 2, 3, \dots$

Let  $V_\lambda$  the submodule corresponding to the eigenvalue  $\lambda = n(n+2)$  of the Casimir. If  $v \in V_\lambda$  then we can find an irreducible submodule  $V_n$  of  $V_\lambda$  and  $v \in V_n$ . Therefore  $V_\lambda = \underbrace{V_n \oplus V_n \oplus \dots \oplus V_n}_{k_n \text{ times}} = k_n V_n$

# $\mathfrak{sl}(3, \mathbb{C})$

$$\mathfrak{sl}(3, \mathbb{C}) = \text{span}(h_1, h_2, x_1, y_1, x_2, y_2, x_3, y_3)$$

$$[h_1, h_2] = 0$$

$$[h_1, x_1] = 2x_1, \quad [h_1, y_1] = -2y_1, \quad [x_1, y_1] = h_1,$$

$$[h_1, x_2] = -x_2, \quad [h_1, y_2] = y_2,$$

$$[h_1, x_3] = x_3, \quad [h_1, y_3] = -y_3,$$

$$[h_2, x_2] = 2x_2, \quad [h_2, y_2] = -2y_2, \quad [x_2, y_2] = h_2,$$

$$[h_2, x_1] = -x_1, \quad [h_2, y_1] = y_1,$$

$$[h_2, x_3] = x_3, \quad [h_2, y_3] = -y_3,$$

$$[x_1, x_2] = x_3, \quad [x_1, x_3] = 0, \quad [x_2, x_3] = 0$$

$$[y_1, y_2] = -y_3, \quad [y_1, y_3] = 0, \quad [y_2, y_3] = 0$$

$$[x_1, y_2] = 0, \quad [x_1, y_3] = -y_2,$$

$$[x_2, y_1] = 0, \quad [x_2, y_3] = y_1,$$

$$[x_3, y_1] = -x_2, \quad [x_3, y_2] = x_1, \quad [x_3, y_3] = h_1 + h_2$$

$\mathfrak{sl}(2, \mathbb{C})$  subalgebras:  $\text{span}(h_1, x_1, y_1)$ ,  $\text{span}(h_2, x_2, y_2)$ ,  
 $\text{span}(h_1 + h_2, x_3, y_3)$

# Weights-Roots (1)

$(\rho, V)$  is a representation of  $\mathfrak{sl}(3, \mathbb{C})$

**Def:**  $\mu = (m_1, m_2)$  is a **weight**  $\iff$   
 $\exists v \in V : \rho(h_1)v = m_1v, \rho(h_2)v = m_2v, v$  is a **weightvector**

**Prop:** Every representation of  $\mathfrak{sl}(3, \mathbb{C})$  has at least one weight

**Prop:**  $\mu = (m_1, m_2) \in \mathbb{Z}^2$

## Weights-Roots (2)

**Def:** If  $(\rho, V) = (\text{ad}, \mathfrak{g})$  weight  $\alpha$  is called **root**

$$\alpha = (a_1, a_2) \rightsquigarrow \text{ad}_{h_1} z = a_1 z, \text{ad}_{h_2} z = a_2 z$$
$$z = x_1, x_2, x_3, y_1, y_2, y_3$$

	root	rootvector
	$\alpha$	$Z_\alpha$
$\alpha_1$	$(2, -1)$	$x_1$
$\alpha_2$	$(-1, 2)$	$x_2$
$\alpha_1 + \alpha_2$	$(1, 1)$	$x_3$
$-\alpha_1$	$(-2, 1)$	$y_1$
$-\alpha_2$	$(1, -2)$	$y_2$
$-\alpha_1 - \alpha_2$	$(-1, -1)$	$y_3$

**Def:**  $\alpha_1$  and  $\alpha_2$  are the **positive simple roots**

# Highest weight

**Def:**  $\mathfrak{h} = \text{span}(h_1, h_2)$  is the maximal abelian subalgebra of  $\mathfrak{sl}(3, \mathbb{C})$ , the **Cartan** subalgebra.

## Theorem

The weights  $\mu = (m_1, m_2)$  and the roots  $\alpha = (a_1, a_2)$  are elements of the  $\mathfrak{h}^*$

$$\mu(h_i) = m_i, \quad \alpha(h_i) = a_i$$

$$\rho(h)v = \mu(h)v \rightsquigarrow \rho(h)\rho(z_\alpha)v = (\mu(h) + \alpha(h))\rho(z_\alpha)v$$

**Def:**  $\mu_1 \succcurlyeq \mu_2 \iff \mu_1 - \mu_2 = a\alpha_1 + b\alpha_2, a \geq 0 \text{ and } b \geq 0$

**Def:**  $\mu_0$  is **highest weight** if for all weights  $\mu \rightsquigarrow \mu_0 \succcurlyeq \mu$

## Definition

$(\rho, V)$  is a **highest weight cyclic representation** with highest weight  $\mu_0$  iff

- 1  $\exists v \in V \rightsquigarrow \rho(h)v = \mu_0(h)v$ ,  $v$  is a **cyclic vector**
- 2  $\rho(x_1)v = \rho(x_2)v = \rho(x_3)v = 0$
- 3 if  $(\rho, W)$  is submodule of  $(\rho, V)$  and  $v \in W \rightsquigarrow W = V$

# Theorem (3)

## Theorem

If  $z_1, z_2, \dots, z_n$  are elements of  $\mathfrak{sl}(3, \mathbb{C})$  then

$$\begin{aligned} & \rho(z_n) \cdot \rho(z_{n-1}) \cdots \rho(z_2) \cdot \rho(z_1) = \\ & \sum_{p=1}^n \left( \sum_{k_1+k_2+\dots+k_8=p} c_{k_1, k_2, \dots, k_8} \cdot \rho^{k_3}(y_3) \rho^{k_2}(y_2) \rho^{k_1}(y_1) \rho^{k_4}(h_1) \rho^{k_5}(h_2) \rho^{k_6}(x_3) \rho^{k_7}(x_2) \rho^{k_8}(x_1) \right) = \\ & \underbrace{\sum_{k_1+k_2+\dots+k_8=n} c_{k_1, k_2, \dots, k_8} \cdot \rho^{k_3}(y_3) \rho^{k_2}(y_2) \rho^{k_1}(y_1) \rho^{k_4}(h_1) \rho^{k_5}(h_2) \rho^{k_6}(x_3) \rho^{k_7}(x_2) \rho^{k_8}(x_1)}_{\text{order } n \text{ terms}} + \left( \text{order } \leq n - 1 \text{ terms} \right) \end{aligned}$$



# Corollary (1)

## Corollary

If  $z_1, z_2, \dots, z_n$  are elements of  $\mathfrak{sl}(3, \mathbb{C})$  and  $(\rho, V)$  is a highest weight cyclic representation with highest weight  $\mu_0$  and cyclic vector  $v$  then

$$\rho(z_n) \cdot \rho(z_{n-1}) \cdots \rho(z_2) \cdot \rho(z_1)v = \sum_{p=1}^n \left( \sum_{\ell_1 + \ell_2 + \ell_3 = p} d_{\ell_1, \ell_2, \ell_3} \cdot \rho^{\ell_3}(y_3) \rho^{\ell_2}(y_2) \rho^{\ell_1}(y_1) \right) v$$

and

$$V = \text{span} \left( \rho^{\ell_3}(y_3) \rho^{\ell_2}(y_2) \rho^{\ell_1}(y_1)v, \quad \ell_i \in \mathbb{N}_0 \right)$$

## Theorem (4)

### Theorem

*Every irrep  $(\rho, V)$  of  $\mathfrak{sl}(3, \mathbb{C})$  is a highest weight cyclic representation with highest weight  $\mu_0 = (m_1, m_2)$  and  $m_1 \geq 0, m_2 \geq 0$*

### Theorem

*The irrep  $(\rho, V)$  with highest weight  $\mu_0$  is a direct sum of linear subspaces  $V_\mu$  where*

$$\mu = \mu_0 - (k\alpha_1 + \ell\alpha_2 + m\alpha_3) = \mu - (k'\alpha_1 + \ell'\alpha_2)$$

*and  $k, \ell, m, k'$  and  $\ell'$  are positive integers.*

## Corollary (2)

### Corollary

*The set of all possible weights  $\mu$  is a subset of  $\mathbb{Z}^2 \subset \mathbb{R}^2 \rightsquigarrow$*

*The set of all possible weights corresponds on a discrete lattice in the real plane*

## Representation (1, 0)

$$\rho(h_1) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \rho(h_2) = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

$$\rho(x_1) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \rho(x_2) = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \quad \rho(x_3) = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\rho(y_1) = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \rho(y_2) = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \quad \rho(y_3) = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix}$$

The dual of the representation (1, 0) is the representation (0, 1), i.e.  $(1, 0)^D = (0, 1)$ . The representation  $(1, 0) \overset{L}{\otimes} (0, 1)$  is the direct sum  $(0, 0) \oplus (1, 1)$ .

# Weight Lattice for $\mathfrak{sl}(3, \mathbb{C})$

Let  $(\rho, V)$  the fundamental representation  $(1, 0)$  then

$$\rho(\mathfrak{sl}(3, \mathbb{C})) \underset{\text{iso}}{\cong} \text{traceless } 3 \times 3 \text{ matrices}$$

**Def:**  $(r, s) \stackrel{\text{def}}{=} \text{Tr}(\rho(r) \cdot \rho(s))$

$(x, y)$  is a non-degenerate bilinear form on  $\mathfrak{g} = \mathfrak{sl}(3, \mathbb{C})$

$$\Leftrightarrow \{(x, \mathfrak{g}) = \{0\} \rightsquigarrow x = 0\}$$

$$\Leftrightarrow \text{Det}(x_i, x_j) \neq 0, \text{ where } x_k = h, x, y$$

## Proposition

$(\cdot, \cdot)$  is a non-degenerate bilinear form on  $\mathfrak{h} \Rightarrow$

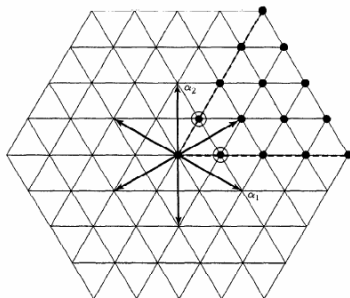
$$\left\{ \forall \nu \in \mathfrak{h}^* \rightsquigarrow \exists h_\nu \in \mathfrak{h} : \nu(h) = (h_\nu, h) \right\} \Rightarrow (h)^* \underset{\text{iso}}{\simeq} \in \mathfrak{h}$$

## Definition

$$\forall \mu, \nu \in \mathfrak{h}^* \rightsquigarrow (\mu, \nu) \stackrel{\text{def}}{=} (h_\mu, h_\nu)$$

$$(\alpha_1, \alpha_1) = (\alpha_2, \alpha_2)$$

$$\begin{aligned}
 (h_{\alpha_1}, h_1) &= \alpha_1(h_1) = 2, & (h_{\alpha_1}, h_2) &= \alpha_1(h_2) = -1 \\
 (h_{\alpha_2}, h_1) &= \alpha_2(h_1) = -1, & (h_{\alpha_2}, h_2) &= \alpha_2(h_2) = 2 \\
 h_{\alpha_1} &= h_1, & h_{\alpha_2} &= h_2 \\
 (\alpha_1, \alpha_1) &= 2, & (\alpha_2, \alpha_2) &= 2, & (\alpha_1, \alpha_2) &= -1 \\
 \|\alpha_1\| &= \|\alpha_2\| = \sqrt{2}, & \text{angle } \widehat{\alpha_1 \alpha_2} &= 120^\circ
 \end{aligned}$$



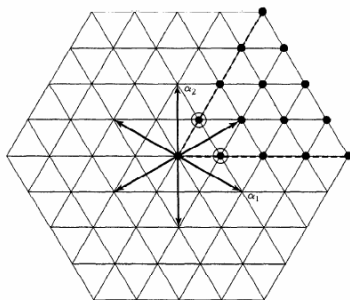
# Fundamental weights (1)

$$\mu_1(h_1) = 1, \quad \mu_1(h_2) = 0, \quad \mu_2(h_1) = 0, \quad \mu_2(h_2) = 1$$

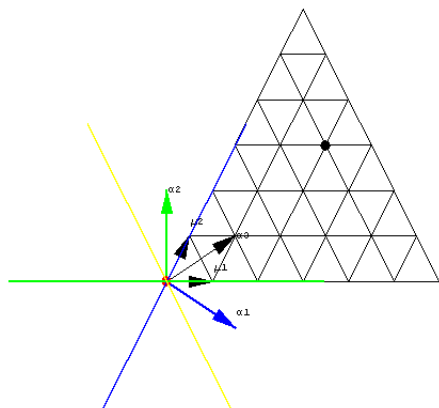
$$\mu_1 = \frac{2}{3}\alpha_1 + \frac{1}{3}\alpha_2, \quad \mu_2 = \frac{1}{3}\alpha_1 + \frac{2}{3}\alpha_2$$

$$\|\mu_1\| = \|\mu_2\| = \sqrt{\frac{2}{3}}, \quad \text{angle } \widehat{\mu_1\mu_2} = 60^\circ$$

$$\mu = m_1\mu_1 + m_2\mu_2, \quad m_i \in \mathbb{N}_0$$



## Fundamental weights (2)





# Chain (1)

$\mu$  weight  $\rightsquigarrow \exists v \in V : \rho(h)v = \mu(h)v$

$\rightsquigarrow \exists p \in \mathbb{N}_o : v_0 = \rho^p(x_i)v \neq 0$  and  $\rho(x_i)v_0 = 0$ ,

$\rho(h)v_0 = (\mu(h) + p\alpha_i(h))v_0$

$\rightsquigarrow \exists q \in \mathbb{N}_o : v_1 = \rho(y_i)^{p+q}v_0 \neq 0$  and  $\rho(y_i)v_1 = \rho(y_i)^{p+q+1}v_0 = 0$ ,

$\rho(h)v_1 = (m(h) - q\alpha_i(h))v_1$ .

$$W = \text{span}(\rho^{p+q}(y_i)v_0, \rho^{p+q-1}(y_i)v_0, \dots, \rho(y_i)^2v_0, \dots, \rho(y_i)v_0, v_0)$$

$(\rho, W)$  is a  $\mathfrak{sl}(2, \mathbb{C})$  submodule

**Def:** If  $\mu$  is a weight and  $\alpha_i, i = 1, 2, 3$  a root, a **chain** is the set of permitted values of the weights

$$\mu - q\alpha_i, \mu - (q-1)\alpha_i, \dots, \mu + (p-1)\alpha_i, \mu + p\alpha_i$$

The weights of a chain (as vectors) are lying on a line perpendicular to the vertical of the vector  $\alpha_i$ . This vertical is a symmetry axis of this chain.

**Prop:** The weights of a representation is the union of all chains

# Theorem (Weyl transform)

## Theorem (Weyl transform)

*If  $\mu$  is a weight and  $\alpha$  any root then there is another weight given by the transformation*

$$S_{\alpha}(\mu) = \mu - 2\frac{(\mu, \alpha)}{(\alpha, \alpha)}\alpha \quad \text{and} \quad 2\frac{(\mu, \alpha)}{(\alpha, \alpha)} \in \mathbb{Z}$$

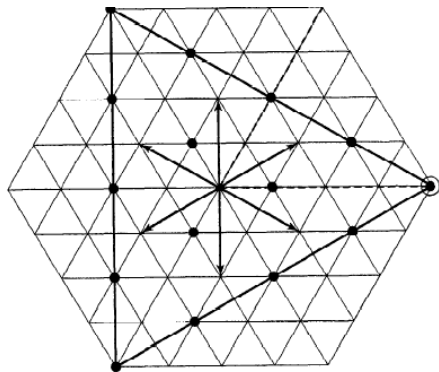
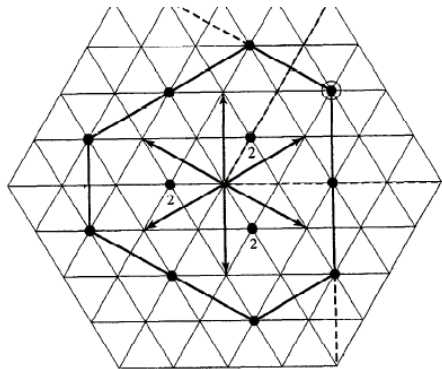


Fig. 5.6. Highest weight (4,0)



**Fig. 5.4.** Highest weight (1,2)

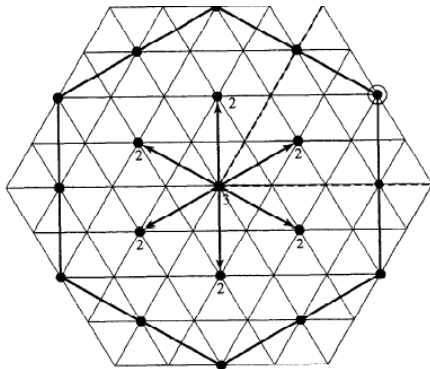


Fig. 5.5. Highest weight (2,2)

# Killing form

$(\rho, V)$  representation of  $\mathfrak{g}$   $B_\rho(x, y) \stackrel{\text{def}}{=} \text{Tr}(\rho(x) \circ \rho(y))$

**Prop:**  $B_\rho([x, y], z) = B_\rho(x, [y, z])$

$\rightsquigarrow B_\rho(\text{ad}_y x, z) + B_\rho(x, \text{ad}_y z) = 0$

## Definition (Killing form)

$$B(x, y) \stackrel{\text{def}}{=} B_{\text{ad}}(x, y) = \text{Tr}(\text{ad}_x \circ \text{ad}_y)$$

$$\mathfrak{g} = \text{span}(e_1, e_2, \dots, e_n) \rightsquigarrow$$

$$\mathfrak{g}^* = \text{span}(e^1, e^2, \dots, e^n), \quad e^i(e_j) = e^i \cdot e_j = \delta_j^i$$

$$B(x, y) = \sum_{k=1}^n e^k \cdot \text{ad}_x \circ \text{ad}_y e_k = \sum_{k=1}^n e^k \cdot [x, [y, e_k]]$$

# Propositions (1)

**Prop:**  $\delta \in \mathfrak{Der}(\mathfrak{g}) \rightsquigarrow B(\delta(x), y) + B(x, \delta(y)) = 0$

**Prop:**  $\tau \in \text{Aut}(\mathfrak{g}) \rightsquigarrow \text{ad}_{\tau x} = \tau \circ \text{ad}_x \circ \tau^{-1} \rightsquigarrow B(\tau x, \tau y) = B(x, y)$

**Prop:**  $\mathfrak{k}$  ideal of  $\mathfrak{g} \rightsquigarrow x, y \in \mathfrak{k} \Rightarrow B(x, y) = B_{\mathfrak{k}}(x, y)$

**Prop:**  $\mathfrak{k}$  ideal of  $\mathfrak{g}$ ,  $\mathfrak{k}^{\perp} = \{x \in \mathfrak{g} : B(x, \mathfrak{k}) = \{0\}\} \rightsquigarrow \mathfrak{k}^{\perp}$  is an ideal.

**Def: Derived Series**

$$\mathfrak{g}^{(0)} = \mathfrak{g}$$

$$\mathfrak{g}^{(1)} = \mathcal{D}(\mathfrak{g}) = [\mathfrak{g}, \mathfrak{g}]$$

$$\mathfrak{g}^{(2)} = \mathcal{D}^2(\mathfrak{g}) = [\mathfrak{g}^{(1)}, \mathfrak{g}^{(1)}]$$

.....

$$\mathfrak{g}^{(n)} = \mathcal{D}^n(\mathfrak{g}) = [\mathfrak{g}^{(n-1)}, \mathfrak{g}^{(n-1)}]$$

$\mathfrak{g}^{(k)}$  is an ideal of  $\mathfrak{g}$

## Definition (Solvable Lie Algebra)

$$\mathfrak{g} \text{ solvable} \iff \exists n \in \mathbb{N} : \mathfrak{g}^{(n)} = \{0\}$$



**Def:** exact sequence,  $\mathfrak{a}$ ,  $\mathfrak{b}$ ,  $\mathfrak{g}$  Lie spaces

$$\mathfrak{a} \xrightarrow{\mu} \mathfrak{g} \xrightarrow{\lambda} \mathfrak{b} \quad \text{Im } \mu = \text{Ker } \lambda$$

**Def:**  $\mathfrak{g}$  extension of  $\mathfrak{b}$  by  $\mathfrak{a}$

$$0 \longrightarrow \mathfrak{a} \xrightarrow[1:1]{\mu} \mathfrak{g} \xrightarrow[\text{epi}]{\lambda} \mathfrak{b} \longrightarrow 0$$

# Solvable Lie Algebra

**Def:** Solvable Lie Algebra  $\mathfrak{g}$  solvable  $\iff \exists n \in \mathbb{N} : \mathfrak{g}^{(n)} = \{0\}$

**Prop:**  $\mathfrak{g}$  solvable ,  $\mathfrak{k}$  Lie-subalgebra  $\rightsquigarrow \mathfrak{k}$  solvable

**Prop:**  $\mathfrak{g}$  solvable,  $\phi : \mathfrak{g} \xrightarrow{\text{Lie-Hom}} \mathfrak{g}' \rightsquigarrow \phi(\mathfrak{g})$  solvable

**Prop:**  $\left\{ \begin{array}{l} \mathfrak{I} \text{ solvable ideal} \\ \text{AND} \\ \mathfrak{g}/\mathfrak{I} \text{ solvable} \end{array} \right\} \Rightarrow \mathfrak{g} \text{ solvable}$

**Prop:**  $\mathfrak{a}$  and  $\mathfrak{b}$  solvable ideals  $\Rightarrow \mathfrak{a} + \mathfrak{b}$  solvable ideal

# Theorem (5)

## Theorem

$$\begin{array}{c} \mathfrak{a} \xrightarrow{\mu} \mathfrak{g} \xrightarrow{\lambda} \mathfrak{b} \\ \text{Im } \mu = \text{Ker } \lambda \end{array} \quad \left\{ \begin{array}{l} \mathfrak{a} \text{ solvable} \\ \text{AND} \\ \mathfrak{b} \text{ solvable} \end{array} \right\} \Rightarrow \mathfrak{g} \text{ solvable}$$

# Theorem (6)

## Theorem

$$\begin{array}{ccccccc} \{0\} & \longrightarrow & \mathfrak{a} & \xrightarrow[\text{1:1}]{\mu} & \mathfrak{g} & \xrightarrow[\text{epi}]{\lambda} & \mathfrak{b} \longrightarrow \{0\} \\ & & & & \downarrow \pi & \swarrow \text{iso} & \\ & & & & \mathfrak{g}/\text{Ker } \lambda & & \end{array}$$

$$\text{Im } \mu = \text{Ker } \lambda$$

$$\mathfrak{g} \text{ solvable} \Rightarrow \left\{ \begin{array}{l} \mathfrak{a} \text{ solvable} \\ \text{AND} \\ \mathfrak{b} \text{ solvable} \end{array} \right\}$$

# Equivalent definitions

## Theorem

- (a)  $\mathfrak{g}$  solvable  $\equiv \mathfrak{g}^{(n)} = \{0\}$
- (b) exists  $\mathfrak{g} = \mathfrak{g}_0 \supset \mathfrak{g}_1 \supset \mathfrak{g}_2 \supset \cdots \supset \mathfrak{g}_n = 0$   
 $\mathfrak{g}_i$  ideals and  $\mathfrak{g}_i/\mathfrak{g}_{i+1}$  abelian.
- (c) exists  $\mathfrak{g} = \mathfrak{h}'_0 \supset \mathfrak{h}'_1 \supset \mathfrak{h}'_2 \supset \cdots \supset \mathfrak{h}'_p = 0$   
 $\mathfrak{h}'_i$  subalgebras of  $\mathfrak{g}$   
 $\mathfrak{h}'_{i+1}$  ideal of  $\mathfrak{h}'_i$  and  $\mathfrak{h}'_i/\mathfrak{h}'_{i+1}$  abelian.
- (d) exists  $\mathfrak{g} = \mathfrak{h}''_0 \supset \mathfrak{h}''_1 \supset \mathfrak{h}''_2 \supset \cdots \supset \mathfrak{h}''_q = 0$   
 $\mathfrak{h}''_i$  subalgebras of  $\mathfrak{g}$   
 $\mathfrak{h}''_{i+1}$  ideal of  $\mathfrak{h}''_i$  and  $\dim \mathfrak{h}''_i/\mathfrak{h}''_{i+1} = 1$ .

$\mathfrak{g}$  solvable Lie algebra  $\Rightarrow \exists \mathfrak{m}$  ideal such that  $\dim(\mathfrak{g}/\mathfrak{m}) = 1$

# Theorem (7)

## Theorem

$\mathfrak{g}$  solvable  $\rightsquigarrow \text{ad}_{\mathfrak{g}} \subset \mathfrak{t}(n, \mathbb{C})$ . There is a basis in  $\mathfrak{g}$ , where **ALL** the matrices  $\text{ad}_x, \forall x \in \mathfrak{g}$ . are **upper triangular** matrices.

$$\text{ad}_x = \begin{pmatrix} \lambda_1(x) & \bullet & \bullet & \bullet & \bullet & \bullet \\ 0 & \lambda_2(x) & \bullet & \bullet & \bullet & \bullet \\ 0 & 0 & \lambda_3(x) & \bullet & \bullet & \bullet \\ & \dots & \dots & & & \\ & \dots & \dots & & & \\ 0 & 0 & 0 & 0 & 0 & \lambda_n(x) \end{pmatrix}$$

## Definition

$\mathfrak{Rad}(\mathfrak{g}) = \text{radical} = \text{maximal solvable ideal} = \text{sum of all solvable ideals}$

**Def:**  $\mathfrak{Rad}(\mathfrak{g}) = \{0\} \iff \mathfrak{g}$  semi-simple

## Theorem (Radical Property)

$\mathfrak{Rad}(\mathfrak{g}/\mathfrak{Rad}(\mathfrak{g})) = \{\bar{0}\} \rightsquigarrow \mathfrak{g}/\mathfrak{Rad}(\mathfrak{g})$  is semisimple

**Prop:**  $\mathfrak{g} = \mathfrak{g}_1 \oplus \mathfrak{g}_2 \rightsquigarrow \mathfrak{Rad}(\mathfrak{g}) = \mathfrak{Rad}(\mathfrak{g}_1) \oplus \mathfrak{Rad}(\mathfrak{g}_2)$

# Nilpotent Lie Algebras

$$\mathfrak{g}^0 = \mathfrak{g}, \quad \mathfrak{g}^1 = [\mathfrak{g}, \mathfrak{g}], \quad \mathfrak{g}^2 = [\mathfrak{g}, \mathfrak{g}^1], \dots, \quad \mathfrak{g}^n = [\mathfrak{g}, \mathfrak{g}^{n-1}] \rightsquigarrow \mathfrak{g}^k \text{ ideals}$$

## Definition

$\mathfrak{g}$  nilpotent  $\iff \mathfrak{g}^n = 0$

$\mathfrak{g}$  nilpotent  $\rightsquigarrow \mathfrak{g}$  solvable

**Prop:**  $\mathfrak{g}$  nilpotent  $\iff \exists m : \text{ad}_{x_1} \circ \text{ad}_{x_2} \circ \dots \circ \text{ad}_{x_m} = 0 \rightsquigarrow (\text{ad}_x)^m = 0$

**Prop:**  $\mathfrak{g}$  nilpotent  $\iff \exists \mathfrak{g}_i$  ideals  $\mathfrak{g} = \mathfrak{g}_0 \supset \mathfrak{g}_1 \supset \mathfrak{g}_2 \supset \dots \supset \mathfrak{g}_r = \{0\}$   
 $[\mathfrak{g}, \mathfrak{g}_i] \subset \mathfrak{g}_{i+1}$  and  $\dim \mathfrak{g}_i / \mathfrak{g}_{i+1} = 1$

**Prop:**  $\mathfrak{g}$  nilpotent  $\Rightarrow$   
 $\exists$  basis  $e_1, e_2, \dots, e_n$  where  $\text{ad}_x$  is strictly upper triangular

**Prop:**  $\mathfrak{g}$  nilpotent  $\Rightarrow B(x, y) = 0$

**Prop:**  $\mathfrak{g}$  nilpotent  $\rightsquigarrow \mathcal{Z}(\mathfrak{g}) \neq \{0\}$

**Prop:**  $\mathfrak{g} / \mathcal{Z}(\mathfrak{g})$  nilpotent  $\rightsquigarrow \mathfrak{g}$  nilpotent



# Engel's Theorem (1)

## Theorem ( Engel's theorem)

$\mathfrak{g}$  nilpotent  $\Leftrightarrow \exists n : (\text{ad}_x)^n = 0$

$\mathfrak{g}$  nilpotent  $\Leftrightarrow \mathfrak{g}$  ad-nilpotent

## Lemma

$$\left\{ \begin{array}{l} \mathfrak{g} \subset \mathfrak{gl}(V) \\ \text{and} \\ x \in \mathfrak{g} \rightsquigarrow x^n = 0 \end{array} \right\} \implies \{ (\text{ad}_x)^{2n} = 0 \}$$

# Engel's Theorem in Linear Algebra

**Prop:**  $\left\{ \begin{array}{l} \mathfrak{g} \subset \mathfrak{gl}(V) \\ \text{and} \\ x \in \mathfrak{g} \rightsquigarrow x^n = 0 \end{array} \right\} \implies \left\{ \exists v \in V : x \in \mathfrak{g} \rightsquigarrow xv = 0 \right\}$

$\mathfrak{m}$  Lie subalgebra of  $\mathfrak{g}$

step #1  $x \in \mathfrak{m} \rightsquigarrow (\text{ad}_x)^m = 0$

$$\begin{array}{ccc} \mathfrak{g} & \xrightarrow{\pi} & \mathfrak{g}/\mathfrak{m} \\ \text{ad}_x \downarrow & & \downarrow \overline{\text{ad}_x} \\ \mathfrak{g} & \xrightarrow{\pi} & \mathfrak{g}/\mathfrak{m} \end{array} \rightsquigarrow (\overline{\text{ad}_x})^m = \bar{0}$$

step #2 **Induction hypothesis**  $\rightsquigarrow \exists \mathfrak{m}$  ideal such that  $\dim \mathfrak{g}/\mathfrak{m} = 1$   
 $\rightsquigarrow \mathfrak{g} = \mathbb{C}x_0 + \mathfrak{m}$

step #3 **Induction hypothesis** and  $\mathfrak{g} = \mathbb{C}x_0 + \mathfrak{m} \rightsquigarrow$   
 $U = \{v \in V : x \in \mathfrak{m} \rightsquigarrow xv = 0\} \neq \{0\} \iff$   
 $\exists v \in V : \forall x \in \mathfrak{g} \rightsquigarrow xv = 0$  and  $\mathfrak{g}U \subset U$

## Engel's Theorem (2)

**Prop :**  $\left\{ \begin{array}{l} \mathfrak{g} \subset \mathfrak{gl}(V) \text{ and} \\ x \in \mathfrak{g} \rightsquigarrow x^n = 0 \end{array} \right\} \implies$   
 $V = V_0 \supset V_1 \supset V_2 \cdots \supset V_n = 0, V_{i+1} = \mathfrak{g}V_i$   
 $\rightsquigarrow (\mathfrak{g})^n V = 0 \rightsquigarrow x_1 x_2 x_3 \cdots x_n = 0$

$V = V_0 \supset V_1 \supset V_2 \cdots \supset V_n = 0, V_{i+1} = \mathfrak{g}V_i$  is a **flag**

### Theorem ( Engel's-theorem)

$$\mathfrak{g} \text{ nilpotent} \Leftrightarrow \exists n : (\text{ad}_x)^n = 0$$

### Theorem

$\mathfrak{g}$  nilpotent  $\Leftrightarrow$  exists a basis in  $\mathfrak{g}$  such that **all** the matrices  $\text{ad}_x, x \in \mathfrak{g}$  are strictly upper diagonal.

**Prop:**  $\mathfrak{g}$  nilpotent  $\Rightarrow \{x \in \mathfrak{g} \rightsquigarrow \text{Tr ad}_x = 0\} \Rightarrow B(x, y) = \text{Tr}(\text{ad}_x \text{ad}_y) = 0$

# Lie Theorem in Linear Algebra

## Theorem (Lie Theorem)

$\mathfrak{g}$  solvable Lie subalgebra of  $\mathfrak{gl}(V) \Rightarrow \exists v \in V : x \in \mathfrak{g} \rightsquigarrow xv = \lambda(x)v, \lambda(x) \in \mathbb{C}$

step #1

## Lemma (Dynkin Lemma)

$$\left\{ \begin{array}{l} \mathfrak{g} \subset \mathfrak{gl}(V) \\ \mathfrak{a} \text{ ideal} \\ \exists \lambda \in \mathfrak{a}^* : \\ W = \{v \in V : \forall a \in \mathfrak{a} \rightsquigarrow av = \lambda(a)v\} \end{array} \right\} \Rightarrow \mathfrak{g}W \in W$$

step # 2  $\mathfrak{g}$  and  $[\mathfrak{g}, \mathfrak{g}] \neq \{0\}, \Rightarrow \{\exists \mathfrak{a} \text{ ideal} : \mathfrak{g} = \mathbb{C}e_0 + \mathfrak{a}\}$

step # 3 induction hypothesis on  $\mathfrak{a} \rightsquigarrow$  Lie theorem on  $\mathfrak{g}$

## Lemma

$\mathfrak{g}$  solvable and  $(\rho, V)$  irreducible module  $\rightsquigarrow \dim V = 1$

## Theorem

$\mathfrak{g}$  solvable and  $(\rho, V)$  a representation  $\Rightarrow$  exists a basis in  $V$  where **all** the matrices  $\rho(x)$ ,  $x \in \mathfrak{g}$  are upper diagonal.

## Theorem

$\mathfrak{g}$  nilpotent and  $(\rho, V)$  a representation  $\Rightarrow$  exists a basis in  $V$  **all** the matrices  $\rho(x)$ ,  $x \in \mathfrak{g}$  satisfy the relation  $(\rho(x) - \lambda(x)\mathbb{I})^n = 0$ , where  $\lambda(x) \in \mathbb{C}$  or the matrices  $(\rho(x) - \lambda(x)\mathbb{I})$  are strictly upper diagonal.

# Propositions (2)

**Prop:**  $\mathfrak{g}$  solvable  $\Rightarrow \mathcal{D}\mathfrak{g} = [\mathfrak{g}, \mathfrak{g}]$  is nilpotent Lie algebra

$$(\rho, W) \prec (\rho, V) \Rightarrow \rho(x) = \left( \begin{array}{c|c} W & * \\ \hline 0 & V/W \end{array} \right)$$

Solvable

$$\rho(x) = \left( \begin{array}{cccccc} \lambda_1(x) & * & * & * & * & \dots \\ 0 & \lambda_2(x) & * & * & * & \dots \\ 0 & 0 & \lambda_3(x) & * & * & \dots \\ 0 & 0 & 0 & \lambda_4(x) & * & \dots \\ & & \dots & & & \\ & & \dots & & & \end{array} \right)$$

Nilpotent

$$\rho(x) = \left( \begin{array}{cccccc} \lambda(x) & * & * & * & * & \dots \\ 0 & \lambda(x) & * & * & * & \dots \\ 0 & 0 & \lambda(x) & * & * & \dots \\ 0 & 0 & 0 & \lambda(x) & * & \dots \\ & & \dots & & & \\ & & \dots & & & \end{array} \right)$$

# Linear Algebra (1)

$$A \in \text{End } V \simeq M_n(\mathbb{C})$$

$p_A(t) = \text{Det}(A - t\mathbb{I}) = \text{characteristic polynomial}$

$$p_A(t) = (-1)^n \prod_{i=1}^m (t - \lambda_i)^{m_i}, \quad \sum_{i=1}^m m_i = n, \quad \lambda_i \text{ eigenvalues}$$

$$V = \bigoplus_{i=1}^m V_i, \quad V_i = \text{Ker}(A - \lambda_i \mathbb{I})^{m_i} \rightsquigarrow p_A(A) = 0 \text{ and } AV_i \subset V_i$$

$$Q_i(t) = \frac{p_A(t)}{(t - \lambda_i)^{m_i}} \Rightarrow \text{If } v \in V_j \text{ and } j \neq i \rightsquigarrow Q_i(A)v = 0$$

**Prop: Chinese remainder theorem**

$Q(t)$ , ( $Q(0) \neq 0$ ) and  $P(t)$ , ( $P(0) \neq 0$ ) polynomials with no common divisors, i.e.  $(Q(t), P(t)) = 1$

$\exists s(t)$ ,  $s(0) = 0$  and  $r(t)$  polynomials such that  $s(t)Q(t) + r(t)P(t) = 1$

**Prop:**  $\exists s_i(t)$  and  $r_i(t)$  polynomials such that  
 $s_i(t)Q_i(t) + r_i(t)(t - \lambda_j)^{m_i} = 1$

**Prop:**  $S(t) = \sum_i^k \mu_i s_i(t) Q_i(t) \Rightarrow v \in V_j \rightsquigarrow S(A)v = \mu_j v$



# Jordan decomposition (1)

## Prop: Jordan decomposition

$A \in gl(V) \rightsquigarrow A = A_s + A_n$ ,  $[A_s, A_n] = A_s A_n - A_n A_s = 0$   
 $A_s$  diagonal matrix (or semisimple) and  $v \in V_j \iff A_s v = \lambda_j v$ ,  
 $A_n$  nilpotent matrix  $(A_n)^n = 0$ , the decomposition is unique

**Prop:**  $\exists!$   $p(t)$  and  $q(t)$  polynomials such that  $A_s = p(A)$  and  $A_n = q(A)$

$E_{ij}$   $n \times n$  matrix with zero elements with exception of the  $ij$  element, which is equal to 1

$$[E_{ij}, E_{kl}] = \delta_{jk} E_{il} - \delta_{il} E_{kj}$$

## Jordan decomposition (2)

**Prop:**  $A = \sum_{i=1}^n \lambda_i E_{ii} \rightsquigarrow$  The eigenvalues of  $\text{ad}_A$  are equal to  $\lambda_i - \lambda_j$   
 $\rightsquigarrow \text{ad}_A E_{ij} = (\lambda_i - \lambda_j) E_{ij}$

**Prop:**  $\text{ad}_A = \text{ad}_{A_s} + \text{ad}_{A_n}$  and  $(\text{ad}_A)_s = \text{ad}_{A_s}$ ,  $(\text{ad}_A)_n = \text{ad}_{A_n}$

# Cartan Criteria (1)

## Lemma

$$\left\{ \begin{array}{l} \mathfrak{g} \subset \mathfrak{gl}(V) \\ x, y \in \mathfrak{g} \rightsquigarrow \text{Tr}(xy) = 0 \end{array} \right\} \Rightarrow [\mathfrak{g}, \mathfrak{g}] = \mathcal{D}\mathfrak{g} = \mathfrak{g}^{(1)} \text{ nilpotent}$$

## Theorem ( 1st Cartan Criterion)

$$\mathfrak{g} \text{ solvable} \Leftrightarrow B_{\mathcal{D}\mathfrak{g}} = 0$$

## Corollary

$$B(\mathfrak{g}, \mathfrak{g}) = \{0\} \rightsquigarrow \mathfrak{g} \text{ solvable}$$

$B$  is non degenerate,  $\mathfrak{a}$  ideal of  $\mathfrak{g} \rightsquigarrow \mathfrak{a}^\perp = \{x \in \mathfrak{g} : B(x, \mathfrak{a}) = \{0\}\}$  is an ideal.

## Cartan Criteria (2)

### Theorem ( 2nd Cartan Criterion)

$\mathfrak{g}$  semisimple  $\Leftrightarrow B$  non degenerate

### Prop

$\mathfrak{a}$  semi-simple ideal of  $\mathfrak{g} \rightsquigarrow \mathfrak{g} = \mathfrak{a} \oplus \mathfrak{a}^\perp$ ,  $\mathfrak{a}^\perp$  is an ideal.

**Prop:**  $\mathfrak{g}$  semisimple,  $\mathfrak{a}$  ideal  $\Rightarrow \mathfrak{g} = \mathfrak{a} \oplus \mathfrak{a}^\perp$

### Theorem

$\mathfrak{g}$  semisimple  $\Leftrightarrow \mathfrak{g}$  direct sum of simple Lie algebras

$$\mathfrak{g} = \bigoplus_i \mathfrak{g}_i, \quad \mathfrak{g}_i \text{ is simple}$$

## Cartan Criteria (3)

### Theorem

$\mathfrak{g}$  semisimple  $\Rightarrow \mathcal{D}\mathfrak{e}\mathfrak{r}(\mathfrak{g}) = \text{ad}\mathfrak{g}$

### Theorem

$\mathfrak{g}$  semisimple  $\Rightarrow \mathfrak{g} = [\mathfrak{g}, \mathfrak{g}] = \mathcal{D}\mathfrak{g} = \mathfrak{g}^{(1)}$

$\mathfrak{g}$  semisimple,  $(\rho, V)$  a representation  $\rightsquigarrow \rho(\mathfrak{g}) \subset \mathfrak{sl}(V)$ .

# Abstract Jordan decomposition

**Prop:**  $\mathfrak{g}$  semisimple  $\rightsquigarrow Z(\mathfrak{g}) = \{0\}$

**Prop:**  $\mathfrak{g}$  semisimple  $\rightsquigarrow \mathfrak{g} \underset{\text{iso}}{\simeq} \text{ad}_{\mathfrak{g}}$

**Prop:**  $\partial \in \mathfrak{Der}(\mathfrak{g})$ ,  $\partial = \partial_s + \partial_n$  the Jordan decomposition  
 $\rightsquigarrow \partial_s \in \mathfrak{Der}(\mathfrak{g})$  and  $\partial_n \in \mathfrak{Der}(\mathfrak{g})$

## Theorem (Abstract Jordan Decomposition)

$\mathfrak{g}$  semisimple  $\rightsquigarrow \text{ad}_x = (\text{ad}_x)_s + (\text{ad}_x)_n$  Jordan decomposition and  
 $x = x_s + x_n$  where  $x_s \in \mathfrak{g}$ ,  $(\text{ad}_x)_s = \text{ad}_{x_s}$  and  $x_n \in \mathfrak{g}$ ,  $(\text{ad}_x)_n = \text{ad}_{x_n}$

# Toral subalgebra

$\mathfrak{g}$  is semisimple

## Definition semisimple element

$x_s$  is **semisimple**  $\iff \exists x \in \mathfrak{g} : x = x_s + x_n$

$x_s$  is semisimple element  $\iff ad_{x_s}$  is diagonalizable on  $\mathfrak{g}$

$x_s$  and  $y_s$  semisimple elements  $x_s + y_s$  is semisimple and  $[x_s, y_s]$  is semisimple.

## Definition Toral/ Cartan subalgebra

Toral subalgebra  $\mathfrak{h} = \{x_s, x = x_s + x_n \in \mathfrak{g}\}$  i.e the set of all semisimple elements

## Theorem

The toral or Cartan subalgebra is abelian

# Lie epimorphism

$\phi$  is a Lie epimorphism  $\mathfrak{g} \xrightarrow[\text{epi}]{\phi} \mathfrak{g}'$  and  $\mathfrak{g}$  simple  $\rightsquigarrow \mathfrak{g}'$  is simple and isomorphic to  $\mathfrak{g}$ .

$\phi$  is a Lie epimorphism  $\mathfrak{g} \xrightarrow[\text{epi}]{\phi} \mathfrak{g}'$  and  $\mathfrak{g}$  semisimple  $\rightsquigarrow \mathfrak{g}'$  is semisimple.

## Proposition

$\mathfrak{g}$  semisimple,  $(\rho, V)$  a representation,  $x = x_s + x_n \rightsquigarrow \rho(x) = \rho(x_s) + \rho(x_n)$  and  $\rho(x_s) = (\rho(x))_s$ ,  $\rho(x_n) = (\rho(x))_n$  the Jordan decomposition of  $\rho(x)$   $\rightsquigarrow \rho(x_n)^m = 0$  for some  $m \in \mathbb{N}$ .

There is some basis in  $V$  where **all** the matrices  $\rho(x_s)$  are diagonal and **all** matrices  $\rho(x_n)$  are either strictly upper either lower triangular matrices.



# Roots construction

$\mathfrak{g}$  semi-simple algebra,

$\mathfrak{h} = \{x_s, x \in \mathfrak{g}, x = x_s + x_n\}$  Toral subalgebra or Cartan subalgebra,

$\mathfrak{h} = \mathbb{C}h_1 + \mathbb{C}h_2 + \dots + \mathbb{C}h_\ell$ .

$\text{ad}_{\mathfrak{h}}$  is a matrix Lie algebra of commuting matrices  $\rightsquigarrow$  all the matrices have common eigenvectors

$\Sigma_i =$  eigenvalues of  $h_i \rightsquigarrow \mathfrak{g} = \bigsqcup_{\lambda_i \in \Sigma_i} \mathfrak{g}_{\lambda_i}$ ,  $\mathfrak{g}_{\lambda_i}$  linear vector space

$x \in \mathfrak{g}_{\lambda_i} \rightsquigarrow \text{ad}_{h_i}x = \lambda_i x$  and  $\lambda_i \neq \nu_i \rightsquigarrow \mathfrak{g}_{\lambda_i} \cap \mathfrak{g}_{\nu_i} = \{0\}$

$$x \in \mathfrak{g}_{\lambda_1} \cap \mathfrak{g}_{\lambda_2} \cap \dots \cap \mathfrak{g}_{\lambda_\ell}, \quad h = c_1 h_1 + c_2 h_2 + \dots + c_\ell h_\ell$$
$$\text{ad}_h x = (c_1 \lambda_1 + c_2 \lambda_2 + \dots + c_\ell \lambda_\ell) x$$

$$\mathfrak{h}^* = \mathbb{C}\mu_1 + \mathbb{C}\mu_2 + \dots + \mathbb{C}\mu_\ell, \quad \mu_i \in \mathfrak{h}^*, \quad \mu_i(h_j) = \delta_{ij}$$

## Definition of the roots

$$\mathfrak{h}^* \ni \lambda = \lambda_1 \mu_1 + \lambda_2 \mu_2 + \dots + \lambda_\ell \mu_\ell \rightsquigarrow c_1 \lambda_1 + c_2 \lambda_2 + \dots + c_\ell \lambda_\ell = \lambda(h)$$

$\lambda$  is a root

$$x \in \mathfrak{g}_\lambda = \mathfrak{g}_{\lambda_1} \cap \mathfrak{g}_{\lambda_2} \cap \dots \cap \mathfrak{g}_{\lambda_\ell} \rightsquigarrow [h, x] = \text{ad}_h x = \lambda(h)x$$

$$\mathfrak{g} = \bigsqcup_{\lambda} \mathfrak{g}_\lambda, \quad \lambda \neq \mu \rightsquigarrow \mathfrak{g}_\lambda \cap \mathfrak{g}_\mu = \{0\}$$

# Root space

$\mathfrak{g}$  semisimple algebra,  $\mathfrak{h} = \{x_s, x \in \mathfrak{g}, x = x_s + x_n\}$  Toral subalgebra  
 $ad_{\mathfrak{h}}$  is a matrix Lie algebra of commuting matrices  $\rightsquigarrow$  all the matrices have common eigenvectors

## Theorem (Root space)

Exists **root space**  $\Delta \subset \mathfrak{h}^*$

- $\mathfrak{g} = \mathfrak{h} \oplus \bigsqcup_{\alpha \in \Delta} \mathfrak{g}_{\alpha}$
- $x \in \mathfrak{g}_{\alpha}, h \in \mathfrak{h} \rightsquigarrow ad_h x = [h, x] = \alpha(h)x$
- $\mathfrak{h}$  is a Lie subalgebra,  $\mathfrak{g}_{\alpha}$  are vector spaces

**Prop:**  $\lambda, \mu \in \Delta \rightsquigarrow \left\{ \begin{array}{ll} [\mathfrak{g}_{\lambda}, \mathfrak{g}_{\mu}] \subset \mathfrak{g}_{\lambda+\mu} & \text{if } \lambda + \mu \in \Delta \\ [\mathfrak{g}_{\lambda}, \mathfrak{g}_{\mu}] = \{0\} & \text{if } \lambda + \mu \notin \Delta \end{array} \right\}$

# Semisimple roots

$\mathfrak{g}$  semisimple Lie algebra,  $\mathfrak{h}$  Toral/Cartan subalgebra

$$B(\mathfrak{g}_\lambda, \mathfrak{g}_\mu) = 0 \text{ if } \lambda + \mu \neq 0$$

$$h, h' \in \mathfrak{h} \rightsquigarrow B(h, h') = \sum_{\lambda \in \Delta} n_\lambda \lambda(h)\lambda(h'), \quad n_\lambda = \dim \mathfrak{g}_\lambda$$

$$\alpha \in \Delta, x \in \mathfrak{g}_\alpha \rightsquigarrow (\text{ad}_x)^m = 0$$

## Proposition

The Killing form is a non degenerate bilinear form on the Cartan subalgebra  $\mathfrak{h}$

$$\{h \in \mathfrak{h}, B(h, \mathfrak{h}) = 0\} \Rightarrow \{h = 0\}$$

# Killing form-non degenerate bilinear form on the Cartan subalgebra

$$\{\forall \alpha \in \Delta, \quad \alpha(h) = 0 \rightsquigarrow h = 0\} \Leftrightarrow \{\text{span}(\Delta) = \mathfrak{h}^*\}$$

$$\{\alpha \in \Delta \Rightarrow -\alpha \in \Delta\} \Rightarrow \{\alpha \in \Delta \rightsquigarrow \mathfrak{g}_{-\alpha} \neq \{0\}\}$$

Killing form  $B$  non degenerate on  $\mathfrak{h} \rightsquigarrow \mathfrak{h}^* \ni \phi \xrightarrow[\text{epi}]{1:1} t_\phi \in \mathfrak{h}, \phi(h) = B(t_\phi, h)$

$x \in \mathfrak{g}_\alpha, y \in \mathfrak{g}_{-\alpha} \rightsquigarrow [x, y] = B(x, y)t_\alpha, t_\alpha \in \mathfrak{h}$  is unique

$$[\mathfrak{g}_\alpha, \mathfrak{g}_{-\alpha}] = \mathbb{C}t_\alpha, \quad \alpha(t_\alpha) = B(t_\alpha, t_\alpha)$$

$$h_\alpha = \frac{2t_\alpha}{B(t_\alpha, t_\alpha)} \rightsquigarrow S_\alpha = \mathbb{C}h_\alpha + \mathbb{C}x_\alpha + \mathbb{C}y_\alpha \underset{\text{iso}}{\simeq} \mathfrak{sl}(2, \mathbb{C})$$

# Propositions (3)

**Prop:**  $\dim \mathfrak{g}_\alpha = 1$

**Prop:**  $\alpha \in \Delta$  and  $p\alpha \in \Delta \rightsquigarrow p = -1$

$$S_\alpha = \mathbb{C}h_\alpha + \mathbb{C}x_\alpha + \mathbb{C}y_\alpha \underset{\text{iso}}{\simeq} \mathfrak{sl}(2, \mathbb{C})$$

$$\mathfrak{g} = \mathfrak{h} \oplus \bigsqcup_{\alpha \in \Delta_+} (\mathbb{C}x_\alpha + \mathbb{C}y_\alpha) = \mathfrak{h} \oplus \mathfrak{g}_+ \oplus \mathfrak{g}_-$$

$$\mathfrak{g}_+ = \bigsqcup_{\alpha \in \Delta_+} \mathbb{C}x_\alpha, \quad \mathfrak{g}_- = \bigsqcup_{\alpha \in \Delta_+} \mathbb{C}y_\alpha$$

Example  $\mathfrak{g} = \mathfrak{sl}(3, \mathbb{C})$

$$\mathfrak{h} = \mathbb{C}h_1 + \mathbb{C}h_2, \quad \mathfrak{g}_+ = \mathbb{C}x_1 + \mathbb{C}x_2 + \mathbb{C}x_3, \quad \mathfrak{g}_- = \mathbb{C}y_1 + \mathbb{C}y_2 + \mathbb{C}y_3$$

$$\beta \in \Delta, \quad \alpha \in \Delta$$

$$\beta \in \Delta \rightsquigarrow \mathfrak{g}_\beta$$

$$\beta + \alpha \in \Delta \rightsquigarrow \mathfrak{g}_{\beta+\alpha} \quad \beta - \alpha \in \Delta \rightsquigarrow \mathfrak{g}_{\beta-\alpha}$$

$$\beta + 2\alpha \in \Delta \rightsquigarrow \mathfrak{g}_{\beta+2\alpha} \quad \beta - 2\alpha \in \Delta \rightsquigarrow \mathfrak{g}_{\beta-2\alpha}$$

...

$$\beta + p\alpha \in \Delta \rightsquigarrow \mathfrak{g}_{\beta+p\alpha} \quad \beta - q\alpha \in \Delta \rightsquigarrow \mathfrak{g}_{\beta-q\alpha}$$

$$\beta + (p+1)\alpha \notin \Delta \quad \beta - (q+1)\alpha \notin \Delta$$

## String of Roots

$$\{\beta - q\alpha, \beta - (q-1)\alpha, \dots, \beta - \alpha, \beta, \beta + \alpha, \dots, \beta + (p-1)\alpha, \beta + p\alpha\}$$

$$\mathfrak{g}_\beta^\alpha = \mathfrak{g}_{\beta-q\alpha} \oplus \mathfrak{g}_{\beta-(q-1)\alpha} \oplus \dots \oplus \mathfrak{g}_{\beta-\alpha} \oplus \mathfrak{g}_\beta \oplus \mathfrak{g}_{\beta+\alpha} \oplus \dots \oplus \mathfrak{g}_{\beta+(p-1)\alpha} \oplus \mathfrak{g}_{\beta+p\alpha}$$

**Prop:**  $(\text{ad}, \mathfrak{g}_\beta^\alpha)$  is an irreducible representation of  $S_a \underset{\text{iso}}{\simeq} \mathfrak{sl}(2, \mathbb{C})$

**Prop:**  $\beta, \alpha \in \Delta \rightsquigarrow \beta(h_\alpha) = q - p \in \mathbb{Z}, \quad \beta - \beta(h_\alpha)\alpha \in \Delta$

# Cartan and Cartan-Weyl basis

## Cartan Basis

$$\begin{aligned} [E_\alpha, E_{-\alpha}] &= t_\alpha, & [h_\alpha, E_\alpha] &= \alpha(t_\alpha)E_\alpha, \\ [E_\alpha, E_\beta] &= k_{\alpha\beta}E_{\alpha+\beta}, & \text{if } \alpha + \beta \in \Delta \\ B(E_\alpha, E_{-\alpha}) &= 1, & B(t_\alpha, t_\beta) &= \alpha(t_\beta) = \beta(t_\alpha) \end{aligned}$$

$$\Delta \ni \alpha \rightarrow t_\alpha \text{ root} \leftrightarrow H_\alpha = \frac{2}{\alpha(t_\alpha)} t_\alpha \text{ coroot}$$

## Cartan Weyl Basis

$$\begin{aligned} [X_\alpha, X_{-\alpha}] &= H_\alpha, \\ [H_\alpha, X_\alpha] &= 2X_\alpha, & [H_\alpha, X_{-\alpha}] &= -2X_{-\alpha} \\ [X_\alpha, X_\beta] &= N_{\alpha\beta}X_{\alpha+\beta}, & \text{if } \alpha + \beta \in \Delta \\ \mathbb{C}X_\alpha + \mathbb{C}H_\alpha + \mathbb{C}X_{-\alpha} &\underset{\text{iso}}{\simeq} \mathfrak{sl}(2) \end{aligned}$$

**Def:**  $(\alpha, \beta) \equiv B(t_\alpha, t_\beta) = \alpha(t_\beta) = \beta(t_\alpha) = (\beta, \alpha)$

**Prop:**  $\ll \beta, \alpha \gg \equiv \frac{2(\beta, \alpha)}{(\alpha, \alpha)} = q - p \in \mathbb{Z}$

**Prop:**  $w_\alpha(\beta) \equiv \beta - \ll \beta, \alpha \gg \alpha, \quad w_\alpha(\beta) \in \Delta$

**Def:** **Weyl Transform**  $w_\alpha : \Delta \longrightarrow \Delta$



# Propositions (4)

**Prop:**  $\beta - \alpha \notin \Delta \rightsquigarrow \ll \beta, \alpha \gg < 0,$

**Prop:**  $\beta + \alpha \notin \Delta \rightsquigarrow \ll \beta, \alpha \gg > 0$

**Prop:**  $\beta(h_\alpha) = \ll \beta, \alpha \gg \in \mathbb{Z}, B(h_\alpha, h_\beta) = \sum_{\gamma \in \Delta} \gamma(h_\alpha)\gamma(h_\beta) \in \mathbb{Z}$

**Prop:**  $B(h_\alpha, h_\alpha) = \sum_{\gamma \in \Delta} (\ll \alpha, \gamma \gg)^2 > 0$

**Prop:**  $\beta \in \Delta$  and  $\beta = \sum_{i=1}^m c_i \alpha_i, \alpha_i \in \Delta \rightsquigarrow c_i \in \mathbb{Q}$

**Prop:**  $\Delta \subset \text{span}_{\mathbb{Q}}(\Delta) = E_{\mathbb{Q}}, E_{\mathbb{Q}}$  is a  $\mathbb{Q}$ -euclidean vector space.

**Prop:**  $(\alpha, \beta) \equiv B(t_\alpha, t_\beta) \in \mathbb{Q}, (\alpha, \alpha) > 0, (\alpha, \alpha) = 0 \rightsquigarrow \alpha = 0$

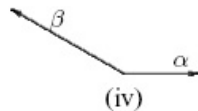
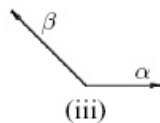
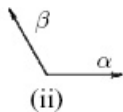
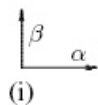
## Propositions (5)

**Prop:** There are not strings with five members  $\leftrightarrow$   
 $\ll \beta, \alpha \gg = 0, \pm 1, \pm 2, \pm 3$

$$\begin{aligned}(\alpha, \beta) &= \|\alpha\| \cdot \|\beta\| \cos \theta \\ \ll \beta, \alpha \gg &= 2 \frac{\|\beta\|}{\|\alpha\|} \cos \theta = 0, \pm 1, \pm 2, \pm 3 \\ \ll \alpha, \beta \gg \cdot \ll \beta, \alpha \gg &= 4 \cos^2 \theta\end{aligned}$$

$\ll \alpha, \beta \gg$	$\ll \beta, \alpha \gg$	$\theta$	$\ \beta\ /\ \alpha\ $
0	0	$\pi/2$	
1	1	$\pi/3$	1
-1	-1	$2\pi/3$	1
1	2	$\pi/4$	$\sqrt{2}$
-1	-2	$3\pi/4$	$\sqrt{2}$
1	3	$\pi/6$	$\sqrt{3}$
-1	-3	$5\pi/6$	$\sqrt{3}$

# Propositions (6)



# Simple Roots

$\Delta = \text{roots}$  is a finite set and  $\text{span}_{\mathbb{R}}(\Delta) = \langle\langle \Delta \rangle\rangle = E = \mathbb{R}^\ell$

## Proposition

$E$  is not a finite union of hypersurfaces of dimension  $\ell - 1$

$\rightsquigarrow E$  is not the union of hypersurfaces vertical to any root

$$\exists z \in E : \forall \alpha \in \Delta \rightsquigarrow (\alpha, z) \neq 0$$

## Definition of positive/negative roots

$\Delta_+ = \{\alpha \in \Delta : (\alpha, z) > 0\}$ , positive roots

$\Delta_- = \{\alpha \in \Delta : (\alpha, z) < 0\}$ , negative roots

$$\Delta = \Delta_+ \cup \Delta_-, \quad \Delta_+ \cap \Delta_- = \emptyset$$

## Definition of Simple roots

$\Sigma = \{\beta \in \Delta_+ : \text{is not the sum of two elements of } \Delta_+\}$

$\Sigma \neq \emptyset$

## Proposition

$\beta \in \Delta_+ \rightsquigarrow \beta = \sum_{\sigma \in \Sigma} n_\sigma \sigma, n_\sigma \geq 0, n_\sigma \in \mathbb{Z}$

# Coxeter diagrams (1)

$$\alpha_i \leftrightarrow \epsilon_i = \frac{\alpha_i}{\sqrt{(\alpha_i, \alpha_i)}} = \text{unit vector}$$

$\Sigma$  simple roots  $\leftrightarrow$  Admissible unit roots

**Def:** Admissible unit vectors  $\mathcal{A} = \{\epsilon_1, \epsilon_2, \dots, \epsilon_n\}$

- 1  $\epsilon_i$  linearly independent vectors
- 2  $i \neq j \rightsquigarrow (\epsilon_i, \epsilon_j) \leq 0$
- 3  $4(\epsilon_i, \epsilon_j)^2 = 0, 1, 2, 3,$

Coxeter diagrams for two points

$$\begin{array}{c} \epsilon_i \\ \circ \end{array} \quad \circ^{\epsilon_j} \quad 4(\epsilon_i, \epsilon_j)^2 = 0$$

$$\begin{array}{c} \epsilon_i \\ \circ \end{array} \text{ --- } \circ^{\epsilon_j} \quad 4(\epsilon_i, \epsilon_j)^2 = 1$$

$$\begin{array}{c} \epsilon_i \\ \circ \end{array} \text{ === } \circ^{\epsilon_j} \quad 4(\epsilon_i, \epsilon_j)^2 = 2$$

$$\begin{array}{c} \epsilon_i \\ \circ \end{array} \text{ - - - } \circ^{\epsilon_j} \quad 4(\epsilon_i, \epsilon_j)^2 = 3$$

## Coxeter diagrams (2)

**Prop:**  $\mathcal{A}' = \mathcal{A} - \{\epsilon_j\}$  admissible

**Prop:** The number of non zero pairs is less than  $n$

**Prop:** The Coxeter graph has not cycles

**Prop:** The maximum number of edges is three

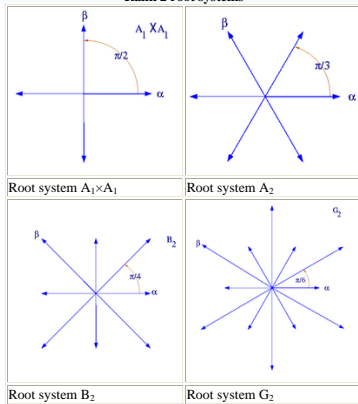
**Prop:** If  $\{\epsilon_1, \epsilon_2, \dots, \epsilon_m\} \in \mathcal{A}$  and  $2(\epsilon_k, \epsilon_{k+1}) = -1$ ,

$|i - j| > 0 \rightsquigarrow (\epsilon_i, \epsilon_j) = 0$


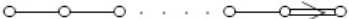




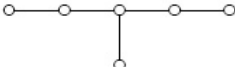
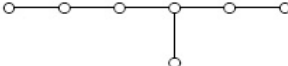
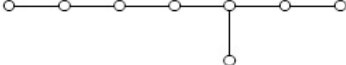
$\epsilon = \sum_{k=1}^m \epsilon_k \Rightarrow \mathcal{A}' = (\mathcal{A} - \{\epsilon_1, \epsilon_2, \dots, \epsilon_m\}) \cup \{\epsilon\}$  admissible

# Coxeter diagrams (3)

Rank 2 root systems



# Dynkin diagrams

Name	Diagram	Rank
$A_l$		$l = 1, 2, 3, \dots$
$B_l$		$l = 2, 3, 4, \dots$
$C_l$		$l = 3, 4, 5, \dots$
$D_l$		$l = 4, 5, 6, \dots$
$G_2$		$l = 2$
$F_4$		$l = 4$
$E_6$		$l = 6$
$E_7$		$l = 7$
$E_8$		$l = 8$



# Serre relations

$$\mathfrak{g} = \mathfrak{h} \oplus \mathfrak{g}_+ \oplus \mathfrak{g}_-, \quad \text{simple roots } \Sigma = \{\alpha_1, \alpha_2, \dots, \alpha_r\}$$

$$x_i \in \mathfrak{g}_{\alpha_i}, \quad y_i \in \mathfrak{g}_{-\alpha_i}, \quad B(x_i, y_i) = \frac{2}{(\alpha_i, \alpha_i)}$$

$$h_i = h_{\alpha_i} \rightsquigarrow \alpha_i(h_i) = 2, \quad \alpha_i(h_j) \in \mathbb{Z}_-$$

## Serre Relations

**Cartan Matrix:**  $a_{ij} = \alpha_j(h_i) = 2 \frac{(\alpha_j, \alpha_i)}{(\alpha_i, \alpha_i)}$

- 1  $[h_i, h_j] = 0$
- 2  $[h_i, x_j] = a_{ij}x_j, \quad [h_i, y_j] = -a_{ij}y_j$
- 3  $[x_i, y_j] = \delta_{ij}h_i$
- 4  $(\text{ad}_{x_i})^{1-a_{ij}} x_j = 0, \quad (\text{ad}_{y_i})^{1-a_{ij}} y_j = 0$

Example  $\mathfrak{sl}(3, \mathbb{C})$  **Cartan Matrix** =  $\begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix}$

# Weight ordering (1)

## Theorem

*The weights  $\mu$  and the roots  $\alpha$  are elements of the  $\mathfrak{h}^*$*

$$h \in \mathfrak{h}, \quad z_\alpha \in \mathfrak{g}_\alpha$$

$$\rho(h)v = \mu(h)v \rightsquigarrow \rho(h)\rho(z_\alpha)v = (\mu(h) + \alpha(h))\rho(z_\alpha)v$$

## Definition of weight ordering

$$\mu_1 \succeq \mu_2 \iff \mu_1 - \mu_2 = \sum_{\alpha \in \Delta_+} k_\alpha \alpha, \quad k_\alpha \geq 0$$

## Weight ordering (2)

If  $(\alpha, \beta) > 0 \rightsquigarrow \alpha - \beta \in \Delta$

If  $\alpha - \beta \notin \Delta \rightsquigarrow (\alpha, \beta) < 0$

If  $\alpha, \beta \in \Sigma \rightsquigarrow (\alpha, \beta) < 0$

Let  $\mu_\alpha \in \text{span}\Delta$  such that  $\mu_\alpha(h_\beta) = (\mu_\alpha, \beta) = \delta_{\alpha,\beta}$ , where  $\alpha, \beta \in \Sigma$

$$\mu_o = \sum_{\alpha \in \Sigma} n_\alpha \mu_\alpha, \quad n_\alpha \in \mathbb{N} \cup \{0\}$$

$$\mu = \sum_{\alpha \in \Sigma} m_\alpha \mu_\alpha, \quad m_\alpha \in \mathbb{Z}_+ \text{ or } \mathbb{Z}_-, \quad \mu \prec \mu_o$$

## Definition of Highest weight

$\mu_0$  is **highest weight** if for all weights  $m\mu \rightsquigarrow \mu_0 \succ \mu$

**Def:**  $(\rho, V)$  is a **highest weight cyclic representation** with highest weight  $\mu_0$  iff

- 1  $\exists v \in V \rightsquigarrow \rho(h)v = \mu_0(h)v$ ,  $v$  is a **cyclic vector**
- 2  $\alpha \in \Delta_+ \rightsquigarrow \rho(x_\alpha)v = 0$
- 3 if  $(\rho, W)$  is submodule of  $(\rho, V)$  and  $v \in W \rightsquigarrow W = V$

# Highest weight representation

## Theorem

Every irrep  $(\rho, V)$  of  $\mathfrak{g}$  is a highest weight cyclic representation with highest weight  $\mu_0$  and  $\mu_0(h_\alpha) \in \mathbb{N} \cup \{0\}$ ,  $\alpha \in \Delta_+$

## Theorem

The irrep  $(\rho, V)$  with highest weight  $\mu_0$  is a direct sum of linear subspaces  $V_\mu$  where

$$\mu = \mu_0 - \left( \sum_{\alpha \in \Delta_+} k_\alpha \alpha \right)$$

and  $k_\alpha$  are positive integers.

## Chain (2)

$\mu$  weight  $\rightsquigarrow \exists v \in V : \rho(h)v = \mu(h)v$

$\rightsquigarrow \exists p, q \in \mathbb{N}_0 : (\rho, W)$  is a  $\mathfrak{g}$  submodule

**Def:** If  $\mu$  is a weight and  $\alpha$  a root, a **chain** is the set of permitted values of the weights

$$\mu - q\alpha, \mu - (q - 1)\alpha, \dots, \mu + (p - 1)\alpha, \mu + p\alpha$$

The weights of a chain (as vectors) are lying on a line perpendicular to the vertical of the vector  $\alpha$ . This vertical is a symmetry axis of this chain.

**Prop:** The weights of a representation is the union of all chains

### Theorem (Weyl transform)

*If  $\mu$  is a weight and  $\alpha$  any root then there is another weight given by the transformation*

$$S_\alpha(\mu) = \mu - 2\frac{(\mu, \alpha)}{(\alpha, \alpha)}\alpha \quad \text{and} \quad 2\frac{(\mu, \alpha)}{(\alpha, \alpha)} \in \mathbb{Z}$$

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Με τη συγχρηματοδότηση της Ελλάδας και της Ευρωπαϊκής Ένωσης



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